E710

😵 Bluetooth







05-0461 Revision 12 System version 10.0

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INTRODUCTION

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Damalini AB

Damalini AB develops, manufactures and markets Easy-Laser[®] measurement and alignment equipment based on laser technology.

We have more than 25 years of experience from measurement tasks in the field and product development. We also provide measurement service, which means that we ourselves use the equipment we develop, and continuously improve it. Because of this we dare to call ourselves measurement specialists.

Do not hesitate to contact us about your measurement problems. Our expertise will help you solve it in an easy way.

Declaration of conformity

Equipment: Easy-Laser® product range

Damalini AB declares that the Easy-Laser[®] product range is manufactured in conformity with national and international regulations. The system complies with, and has been tested according to the following requirements:

EMC Directive	2004/108/EG
Low Voltage Directive	2006/95/EC
Laser Classification	Europe: SS_EN 60825-1
	USA: CFR 1040.10/11
RoHs Directive	2011/65/EU
WEEE Directive	2012/19/EU

The calibration of the equipment fully complies with ISO9001:2008 #7.6

For Bluetooth® devices: This device complies with Part 15 of the FCC Rules.

Operation is subject to the following two conditions:

(1) this device may not cause harmful interference

(2) this device must accept any interference received, including interference that may \sim cause undesired operation.



Disposal of old electrical and electronic equipment (Applicable throughout the European Union and other European countries with separate collection programs)

This symbol, found on product or on its packing, indicates that this product should not be treated as household waste when disposed of.

It should be handed over to an applicable collection point for the recycling of electrical and electronic equipment. By ensuring this product is disposed correctly, you will help to prevent potential negative consequences to the environment and human health. For more detailed information about the recycling of this product, please contact your local city office, household waste disposal service or the retail store where you purchased this product.

Quality certificate

Damalini AB is ISO 9001:2008 certified. Certificate number 900958.

Damalini AB confirm, that our products are produced according to applicable national and international regulations and standards. All components are checked before assembly and final products are tested in functionality and visually checked before delivery

The calibration of the equipment fully complies with ISO9001: 2008 #7.6

Limited warranty

This product is manufactured under Damalini's strict quality control system. Should the product fail within two (2) years from the date of purchase under normal usage conditions, Damalini will repair or replace the product free of charge.

- 1. Using new or refurbished replacement parts.
- 2. Exchange the product with a product that is new or which has been manufactured from new or serviceable used parts and is at least functionally equivalent to the original product.

Proof of purchase date should be confirmed, and sent together with a copy of the original purchase document.

Warranty is valid under normal usage described in the user's manual appended with the product. The warranty comprises failure on Easy-Laser[®] product that could be related to material and/or fabrication errors. The warranty is valid only in the country of purchase.

The warranty is not valid in the following cases:

- If the product is broken due to mishandling or incorrect operation
- If the product has been exposed to extreme temperature, calamity, chock or high voltage.
- If the product has been modified, repaired or disassembled by unauthorized personnel.

Compensation for possible damage due to failure on Easy-Laser[®] product is not included in the warranty. Freight cost to Damalini is not included in the warranty.

Note!

Before delivery of the product for warranty repair, it is the responsibility of the buyer to backup all data. Data recovery is not included in the warranty service and Damalini is not responsible for data that may be lost or damaged during transit or repair.

Lithium Ion battery limited warranty

Lithium ion batteries inevitably lose power during their lifetimes, depending on usage temperatures and the number of charging cycles. Therefore, the internal rechargeable batteries used in the E-series are not included in our general 2-year warranty. There is a 1 year warranty for the battery capacity not to fall below 70 % (a normal change means that the battery must have more than 70 % capacity after more than 300 charging cycles). A 2 year warranty applies if the battery becomes unusable because of a manufacturing fault or factors that Damalini AB could be expected to have control of, or if the battery displays abnormal loss of capacity in relation to use.

Extended warranty

Easy-Laser® Measurement and Alignment Systems meet the highest quality standards! For this reason, we have extended the warranty to you to a total of 3 years — free of charge!

The prerequisite for a warranty extension is that you register your system parts on the Internet within 6 months of purchase. The warranty period begins on the date of purchase. The warranty extension applies to all products in accordance with the Easy-Laser® Warranty requirements.

Safety precautions

Easy-Laser[®] is a laser instrument in laser class II with an output power less than 1 mW, which requires the following safety precautions:

- Never stare directly into the laser beam
- Never aim the laser beam at anyone else's eyes.

Note!

Opening the laser units can result in hazardous radiation, and will invalidate the manufacturer warranty.

If starting the machine to be measured would result in injuries, the possibility to unintentionally start it must be disabled before mounting the equipment, for example by locking the switch in the off position or removing the fuses. These safety precautions should remain in place until the measurement equipment has been removed from the machine.

Note!

The system should not be used in explosive risk areas.

Service and calibration

Our Service centres will quickly assist you if your measurement system need to be repaired or when it is time for calibration.

Our main Service centre is located in Sweden. There are several local Service centres that are certified to carry out limited service and repair. Contact your local Service centre first before sending your equipment for service or repair. All Service centres are listed on our web site under Service and Calibration.

Before sending your measuring system to our main Service centre, please fill in the online Service and Repair report. www.easy-laser-service.com



Manuals as PDF

You can download our manuals in pdf format from our website. The pdf's are also available on the USB memory stick that is delivered with most systems.

EasyLink

The new version of our database program EasyLink is available on the USB memory stick that is delivered with most systems. You can always download the latest version from damalini.com>download>software.



Travelling with your measurement system

When travelling by airplane with your measurement system we strongly recommend that you check which rules apply for each airline company. Some companies/countries have limitations for checked baggage when it comes to items including batteries. For information about Easy-Laser® batteries, please see system unit details in the end of this manual. It is also good practice to remove the batteries from the equipment, when possible, e.g. D22, D23 and D75.

Compatibility

The E-series is not compatible with previous analogue units from the D-series. You can however continue to use previous brackets.

Disclaimer

Damalini AB and our authorized dealers will take no responsibility for damage to machines and plant as a result of the use of Easy-Laser[®] measurement and alignment systems.

Copyright

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We might change and correct the manual in later issues without further information. Changes to the Easy-Laser[®] equipment may also affect the accuracy of the information.

May 2015

Just En

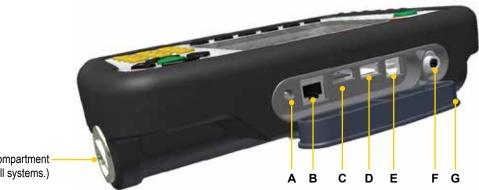
Fredrik Eriksson Quality Manager, Damalini AB

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DISPLAY UNIT



- **A** Connection for external power.
- B Network connection. (Not available on all systems.)
- C External connection. Use for projector for example. (Not available on all systems.)
- **D** USB A (master). Use for USB memory.
- E USB B (slave). Use for connecting to a PC.
- F Connection for Easy-Laser® equipment.
- G Protective cover.



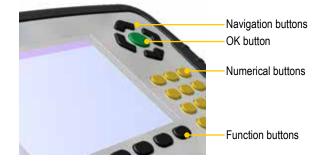
Battery compartment – (Not available on all systems.)

Reset the Display unit

Press and hold the On/Off button to reset the Display unit.

Navigation buttons

To navigate on the screen, use the navigation buttons. The selected icon is marked with a yellow frame. The navigation buttons are also used to move between the icons in a submenu and to change the values in the fields.



OK buttons

There are two green **OK** buttons and they both work in the same way. Press **O** to select the currently selected icon for example.

Function buttons

The icons above the function buttons change depending on which view is currently displayed on screen.

Below is a list of the most common icons.

-	Back to previous view. Press and hold to leave current program.
	Back. There is no "previous view". Leave the current program.
	More. Contains a submenu with general functions, such as (Control panel) and (Save file).

Submenus

The icons formed as an arrow contain a submenu. Use the navigation buttons to navigate in a submenu. Press **()** to select.



Function button with arrow contains submenu

Status bar

The Status bar contains additional information such as warning icon, current time and Bluetooth[®] connection.



Measurement unit. Change units via Settings.

The yellow arrow indicates that there are sub-menus

There are also text messages regarding:

- The selected icon.
- Hints on what information you are expected to fill in.

Status bar icons

	Warning . Select the function button to get additional information regarding the warning.
	Warning . Displayed when the coordinates has been rotated in the detector. Go to Control panel to rotate coordinates.
	Display unit is low in battery.
1	Display unit charging . Indicating that a power adaptor is plugged in.
X	Hourglass. The Display unit is in the middle of a task.
	Measurement progress. Time depending on which filter you have selected.
<mark>w</mark> 1	Selected filter.
Ľ	Peripheral . Indicates that a peripheral device is plugged in, such as a projector.
*	Bluetooth [®] . Indicates that the Bluetooth [®] functionality is activated. The number beside indicates the number of Bluetooth [®] units connected.
₽	Printing report on thermal printer. The thermal printer is optional equipment.
-	Printing performed OK.
4	Printing problem.

Screen dump

It is possible to take screen dumps of what is currently displayed on screen. You can e-mail the screen dump or use it for reports.

Take a screen dump

- 1. Press and hold the numeric button period (.) for 5 seconds.
- 2. An hour glass is displayed on the status bar.
- 3. The screen dump is saved in the file system as a .jpg file. It is named with current date and time. Select **Constant** to open saved files. *See "Measurement file handling" on page 11.*

LED lights

Right indicator

Yellow Flashing: The internal battery in the Display unit is charging.	
Tenow The method outery in the Display unit is charging.	

Left indicator

Left indicator has several functions and colours:

Red/Blue	Quick flashing: Reprogramming the system.
Red	Flashing: Warning, for example low battery.
Blue	Flashing: Searching for detectors equipped with Bluetooth [®] .
	Fixed light: Connected to detectors equipped with Bluetooth®.
Green	Flashing: Display unit is starting.
	Fixed light: The internal battery in the Display unit is fully charged.
Light blue	Flashing: Backlight is off, but the Display unit is still on. Press any button to activate the Display unit.

Battery

Select **Select** to display the Battery view. This view gives you a good overview of the battery status of all connected equipment.



The E-series is not compatible with units from the D-series.

Note!

When finished working for the day, charge the whole system. Plug in the power adaptor to the Display unit and connect the measuring units by using cable.

Charge the Display unit

The Display unit can be used from -10°C to +50°C. Charge the Display unit within the temperature range of ± 0 °C to +40°C.

Note!

If you shut the Display unit off while charging, it will charge faster.

Power adaptor

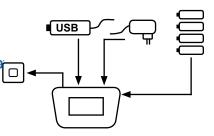
With the power adaptor plugged in, you can keep on working.

A PC via USB cable

While you have this connection, you can open the files in the Display unit via the explorer in your PC. However, the Display unit is locked.

Dry cell batteries

When you get a battery warning, insert four R14 dry cell batteries in the battery compartment. This will prolong the power of the Display unit so that you can finish your measurement. However, if the internal battery is completely empty, the dry cell batteries do not have enough power to start up the Display unit.



Charge the Detector/Measuring units

The Detectors and Measuring units are charged by the Display unit when connected by cable. If you are using Bluetooth[®] units, switch to cable when the battery in the Detector/Measuring unit is low.

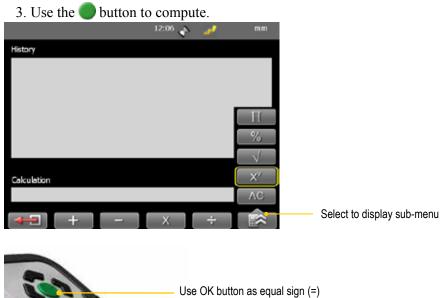
Charge the Bluetooth® units

The Bluetooth[®] units are powered by the Detector/Measuring units. To save energy, the Bluetooth[®] units will only connect when you are using a measurement program. There is no power switch on the unit. To switch off, simply unplug the unit. *See "Bluetooth*® *set up" on page 21.*

Calculator

The calculator is found on the Start view and Control panel (

- 1. Select **and** and **b** to open the calculator.
- 2. Use the numerical buttons and function buttons to enter values.

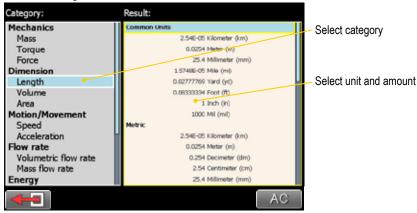


Unit converter

The unit converter is found on the Start view and Control panel (

- 1. Select and to open Unit converter.
- 2. Select a category. Move using the navigation buttons up and down.
- 3. Press navigation button right. The result column is activated.
- 4. Select a unit to convert from.
- 5. Enter an amount. The other units are recalculated.

In the example below, one inch is selected.



Measurement file handling

Save file

- 1. Select and to save your measurement.
- 2. Enter a file name. The date and time will automatically be added to the file name. The measurements that you save will be available to other users as well.
- 3. Press on to save the file.

File manager

Select found on the start view and Control panel) to open saved measurements. The File manager is displayed. Here you can easily when and from which program the file was saved.

Press open a measurement file.



Function buttons

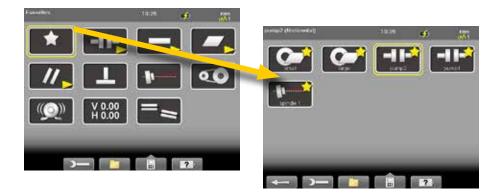
	Back to previous view.
Â	"Report" on page 14. "Open file as template" on page 13.
	"Print file (Optional)" on page 14.
	AZ Sort files alphabetically.
	Sort files by measurement program.
	Sort by time.
	Show all files.
	xml Show only xml files.
	pdf Show only pdf files.
	Show only jpg files.
	Show only Favourites. See "Favourites" on page 12.
	"Copy file to USB memory" on page 13.
Ē	Delete files. Delete all displayed files or only selected file.

Favourites

It is possible to save a measurement as a Favourite. A Favourite can be used for example when you have many flanges or machines with the same dimensions. This way you do not have to enter the same distances or tolerances every time. When you have saved as Favourite, a new icon is displayed on the start screen.

Create a favourite

- 1. Select **I** to open the File manager and select a file.
- 2. Select and to save the selected file as a Favourite.
- 3. Go to the start screen and select **to** see all favourites.
- 4. Press OK to open a Favourite. All distances are filled in.



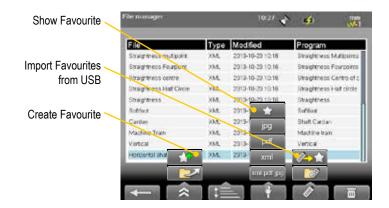
Import favourites

The favourite files are saved in the folder Favourites in the Display unit.

- 1. Plug in the Display unit to a PC and open the Favourites folder.
- 2. Copy the .FAV (favourite) file to the root of an USB memory stick.
- 3. Connect the USB stick to a Display unit and select and and to import.

Delete favourite

- 1. Select **[11]** to open the File manager and select a file.
- 2. Select and to show all Favourite files.
- 3. Select a file and 💼 .



Open file as template

You can open a saved measurement and use it to make a new measurement. This is very useful when you have many flanges or machines with the same dimensions for example. This way you do not have to enter the same distances every time.

- 1. Select (found on the Start view and Control panel). The File manager is displayed.
- 2. Select a file in the list and select *E*. The Edit distance view is displayed.
- 3. Change distances if needed and proceed to measuring view.

Copy file to USB memory

You can easily copy a saved measurement or other files to a USB memory.

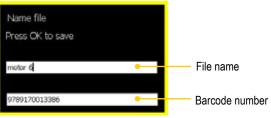
- 1. Insert a USB memory.
- 2. Select the file you want and select
- 3. A folder is automatically created on the USB memory. The file is saved in the folder \Damalini\archive\.

Barcode

Save file with barcode

The barcode scanner is not included in all systems. The first time you measure a machine, you stick a barcode on the machine and save the measurement together with the scanned barcode. Next time you align the same machine, all you need to do is scan the barcode and all machine data is read.

- 1. Scan the barcode on the machine.
- 2. Enter a file name.
- 3. Press **o** to save the file. All measurement data is saved together with the barcode.



The barcode number is added to the file name.

When you connect the Display unit to a PC the whole file name is shown:

Namn	2009-10-05 01	-45-05.6.bob	30ML	Senast ändrad 2009-10-05 13:45	Typ XML-dokument	Storfek 22 kB	INFO CONTRACTOR
tand.	lard.2009-10-1	3 03-58-05.6.	JMX.dod	2009-10-13 15:58	XML-dokument	17 kB	
Small	flange.2009-1	0-21 02-30-0	9.6.bob.XML	2009-10-21 14:30	XML-dokument	40 KB	
🔄 pump	p 1.2010-03-17	11-58-05.5.b	ob.EAN9789170013386.XML	2010-03-17 11:58	XML-dokument	5 kB	
📄 pump	p 1.2010-03-1	11-57-17.5.b	06.EAN9789170013316.XML	2010-03-17 11:57	XML-dokument	5 kB	
e name	Date ar	nd time	User Barco	de number		Bar	code reader

Open file with barcode

• Start the Display unit and scan the barcode. The **latest** measurement that was made and saved with this barcode is automatically opened.

OR

• Select **Control** to open File view. Scan the barcode on the machine. All measurements saved with this barcode are shown.

Print file (Optional)

Part no. 03-1004

The thermal printer is optional equipment.

- 1. Save the measurement. To print from a Shaft program, you need to open a saved measurement before you can print a report.
- 2. Connect the thermal printer and select and .
- 3. The progress is displayed on the status bar.



EASY-LASE

You can also save a measurement, download the pdf-report to your PC and print the pdf-report.

Report

A report is generated and saved in the filing system. You can not open an old measurement and save it again (program Machine train is an exception to this). You can however generate a new report from an opened file. This means you can for example change the language and make a new report from the opened measurement. You can download the report to a PC and print it.

Company logo

You can replace the logo on the report with your own .jpg file.

- 1. Name your logo logo.jpg. The default logo has the proportions of 230x51 pixels.
- 2. Connect the Display unit to your PC using the USB-cable.
- 3. Place your image in the Display unit's folder Damalini/custom/reports/ logo.

File extensions (for example .jpg) are often hidden in the Explorer window. To display file extensions do the following: Open an Explorer window and press Alt to show menu. Select Tools > Folder options. Click the View tab > Advanced settings > Clear the Hide extensions for known file types check box.

Date format

By default, the date and time format is set to Central European Time (CET). You can change the date and time format used in your PDF reports.

See "Date and time" on page 16.

Download file to PC

- 1. Start the Display unit.
- 2. Connect the USB cable between the Display unit and PC.
- 3. While you have this connection, the Display unit is blocked.
- 4. View and/or copy the files to the PC.

EasyLink

You can also use our database program EasyLink to view the files on your PC. EasyLink is available on the USB memory stick that is delivered with most systems. You can always download the latest version from damalini. com>download>software.

Control panel

Select and will be default next time you start the system.



Nofe! All settings are not available for all systems.

Filter

Select when the Filter view.

The filter you select on the Filter view will be saved as a personal setting.

If the laser beam passes through air with varying temperature, this may influence the direction of the laser beam. If measurement values fluctuate, this could mean unstable readings. Try to reduce air movements between laser and detector by, for instance, moving heat sources, closing doors. If the readings remain unstable, increase the filter value (more samples will become available to the statistical filter).

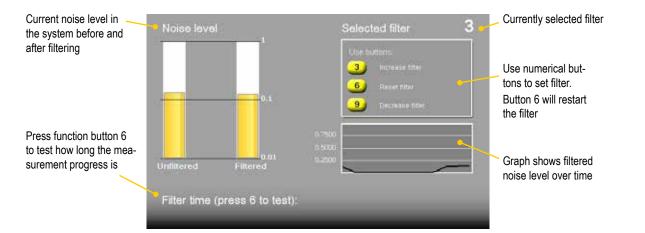


Select filter

Use as short a time as possible that still produces acceptable stability during the measurement. Default is set to **1**. Normally you will use a filter value of 1-3. If you set the filter type to 0, no filter will be used. Use the numerical buttons 3, 6 and 9 to set the filter. In the Filter view but also when you are using a measuring program.



Use numerical buttons to select filter



Unit and resolution

Personal setting

Select to open the Units and resolution view. Use the navigation buttons to move between the fields. Set Metric or Imperial and which resolution you want to use. Default is set to 0.01 mm (0.4 mil). The selected unit is shown on the Status bar.

To A STOC	
Aetric	0.1 mm
mperial	0.01 mm
	0.001 mm

Note!

It is possible to select 0.0001mm only in the E940 system. For E420, only 0.01mm is possible.

Detector rotation

Personal setting

The coordinate system can be rotated 90°. Select **b** to open the Detector rotation view. When you have rotated the coordinates, a warning is displayed on the Status bar. Detector rotation will only affect detectors with two axis.

		Warning displayed on Status bar
	Detector rotation:	Status bai
-85	0"	
8	90"	
		Detector rotation view

Date and time

Select 22 to open the Date and Time view. Set the date and time. Default is set to Central European Time. (CET)



Date and time view

Select **E** to set the date format used in your PDF reports.

124	
Report date and time format	
2010-05-07 10:32	
7/5/2010 10:32 AM	
7-May-2010 10:32	
07.05.2010 10:32	
07/05/2010 10:32	
2010/5/07 10:32	
5/7/2010 10:32 AM	
07.05.2010 10:32	

Date and time used in PDF reports

Language

Personal setting

Select **we select** to open the Language view. Default is set to English. Use the navigation buttons to select a language. Press **b** to save changes.

۲		
Hipptexta 中文 Português Suomi Poccieo 한국어 Nederlands Polska 中國傳統		
		Language view

User

Select **to** open the Users view. A user account is used for storing your personal settings.

Use the function buttons **to add or remove users**. To switch user, simply select the user you would like to switch to and press **.**

8		
User		
User User Rolf		
Rof		
_		User view

Backlight

Personal setting

Select to open the Backlight view. Use the navigation buttons to move between the fields. Press to save changes. When backlight is off, the left LED signal will flash to indicate that the Display unit is still on.

Backlight level

Adjust the backlight to make it easier to read in bright sunlight. Remember however that a high contrast consume more battery power. Default is set to 50%.

Reduce after

Set time before backlight reduction as a way to save energy. The Display unit will be dimmed, but is still on. Default is set to Never.

Off after

Set time before backlight off. Default is set to Never.

acklight level	Reduce after	Offatters
10 %	Never	Never
25 %	5 seconds	5 minutes
50 %	10 seconds	10 minutes
75 %	20 seconds	20 minutes
100 %	30 seconds	30 minutes
	60 seconds	60 minutes
	120 seconds	120 minutes

Backlight view

Automatic power off

Personal setting

Select 2 to open the Automatic off view. Select how much time before automatic power off. Use the navigation buttons to select. Press to save changes.

Automatic power off view

Note!

Measurements in progress will not be saved in the event of an Automatic power off.

Information

Select **i** to display the information regarding serial number and version of the equipment.

i		
Serial number 355 Version: System 8:0 Beta2	EASY-LASER We Make IP Easy!	
_	_	Information view

VGA

(Not available on all systems.)

Makes it possible to show display unit screen image with a projector, for example in a training context. Must be factory installed on order.

Select **I** to open the VGA view.



System update

Download update file

- 1. Go to www.damalini.com > Download > Software > E series Display unit Firmware Update.
- 2. Download the update file to your PC.
- 3. Unzip the file.
- 4. Copy the .elu file to the root of a USB memory.

Install update file

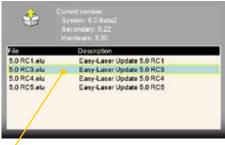
- 1. Start the Display unit. Make sure that the internal battery of the Display unit is charged. The battery symbol should be at least yellow.
- 2. Insert the USB memory in the Display unit. Do not remove the USB memory until the update is finished.
- 3. Select and to display the System update view.
- 4. Select the update file and press O.

seconds to restart the Display unit.

- 5. Select . The installation starts.
- 6. The Display unit will automatically restart when the installation is finished and the Main menu is displayed.

During restart, the screen turns black for up to one minute. When the main menu is displayed, it can "freeze" (no response when you press buttons). If this happens, press the On/Off button for at least 15

Save .elu file on a USB memory.



Select the .elu file.



Main menu is automatically displayed after restart.

Font package

Note!

Some of the early E-series systems was not installed with Unicode fonts. To install the latest system updates, you need to install the font package with Unicode fonts. Check if you need to install:

- 1. Select **2** and **b** to display the Language view.
- 2. Check if you have Chinese installed. If Chinese is installed, you already have the correct Font package. If not, please go to www.damalini.com > Download > Software > Eseries Display unit Font package update and follow the instructions above to install.



Chinese installed? No need to update with Font package.

License

It is easy to upgrade your Display unit.

- 1. Contact your Easy-Laser® distributor if you wish to upgrade your Display unit.
- 2. An e-mail will be sent to you with information on how to download the update file.
- 3. Save the file to the root of the file system to a USB memory stick or directly to the Display unit.

Save file on USB

- 1. Save the downloaded license file to a USB memory stick.
- 2. Insert the USB memory stick in the Display unit.
- 3. Select **2** and **2** to display the License view.

License	Expires	Days left	Demo
Not license			
Not license			
Group			
Group			
Group			
Not license			
Group			
Group			
	Not license Not license Group Group Not license Group	Not license Not license Group Group Group Not license Group	Not license Not license Group Group Group Not license Group

- 4. Select **1** to search for licenses.
- 5. Press b to import license.

Save file to Display unit

- 1. Connect the Display unit to a PC.
- 2. Save the license file to the root of the Display unit's storage.

💽 Ordna 🔹 🔠 Vise 🔹 🛒	Vise	bildspel 🧶 Brann	The second s		<i>w</i>
Fevorillänkar		Namn	Storlek	Fotodetum	Ta
Julia Sökningar Nyligen ändrat Mer 19		Demalini KS 11.78.0.elu	11 317 kB		
Mappar	^	- H			

- 3. Select and to display the License view.
- 4. Select to search for the new license file. A window is displayed.
- 5. Disregard the text and select 🗹 . The license file is installed and full functionality is achieved.

Bluetooth® set up

Bluetooth[®] wireless technology makes it possible for Display unit and Detector to exchange data without using cables.

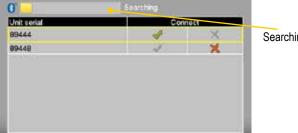


Some detectors have built-in Bluetooth[®], others have a separate Bluetooth unit that you attach to the detector. *Please see Technical data for more information*.

Set up

This is only necessary when adding new Bluetooth® units to the list.

- 1. Select **I** to open the Bluetooth[®] view.
- 2. Select **Select** to search for Bluetooth[®] units.
- 3. The view is updated with the Easy-Laser[®] Bluetooth[®] units you can connect to.



Searching for Bluetooth® units

- 4. Select the unit you want to connect to and select . The unit will automatically be connected when you start a measurement program.
- 5. Press on to save changes and to leave the Bluetooth[®] view.
- 6. Enter a measurement program. The Display unit will connect to the selected units. While connecting, the left LED indicator is flashing with a blue light which will turn to a fixed blue light once connected.
- 7. An icon on the status bar will indicate how many Bluetooth[®] units are connected.



One Bluetooth® unit connected

Function buttons

-	Back to Control panel. Changes made in the table are saved.
	Search for Bluetooth [®] units.
	Cancel search. Use if your Bluetooth [®] unit is already found.
Ē	Remove a Bluetooth [®] unit from the list.
 ✓× 	Connect the unit. The unit will automatically connect when you start a measurement program.
× 🗙	Disconnect the unit. The unit will remain in the list.

Use only one Bluetooth[®] unit

Many of our systems are delivered with two Measuring units. In some cases you might want to use only one unit together with a laser transmitter. By default both units are set to "Connect \checkmark ". If the unused unit is set to "Connect \checkmark ", the system will keep on trying to connect to it, even if it is not plugged in.

- 1. Attach the Bluetooth unit to the detector.
- 2. Select **I** to open the Bluetooth[®] view.
- 3. Set the Bluetooth \mathbb{R} unit you want to use to \checkmark .
- 4. Make sure that the other units are set to \mathbf{X} .
- 5. Enter a measuring program.

The Display unit will connect to the selected unit. This may take a couple of minutes.

Note!

Remove Bluetooth[®] *unit from the Measuring unit before putting the equipment in the carrying case. If attached, it will discharge the Measuring unit.*

Bluetooth® information

cause undesired operation.

This device contains FCC ID: PVH0925 IC: 5325A-0925 This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions; (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may

CHOOSE PROGRAM

Preparations

Before starting a measurement, there are several things that are good to check to ensure a good and accurate measurement.

- · Ensure a good measurement environment. Strong sunlight, warning lights, vibrations and temperature gradients can affect the readings.
- Make sure the surfaces are clean.
- Ensure that the foundation of the machine is stable.
- Check for play and clearance in the bearing.

Values V 0.00

Shows live readings from S and M units.



Horizontal For alignment of horizontal machines.



Vertical For alignment of vertically mounted machines.



Cardan For alignment of cardan-shaft-coupled/centre-offset machines.



Machine train For machine trains with two or more couplings.



Flatness

Straightness For straightness measurement of machine bases, bearing journals, machine tools, etc.

Program to measure flatness of machine bases, machine tables, etc.



Flange Flatness Measure 1 to 5 circles on a flange.



Flange Section Use for large flanges. The flange is divided into four sections.



Twist Measure twist on an object by taking two diagonal measurements.



BTA For alignment of belt and chain drives.



VIbrometer Shows the vibration level in "mm/s" and bearing condition value in "g".



Offset and Angle Shows centre offset and angular error between two shafts, for example.



Softfoot Check to ensure that the machine is resting evenly on all its feet.

Measure roll parallity using a penta prism and a precision level.



Parallelism B

Parallelism A

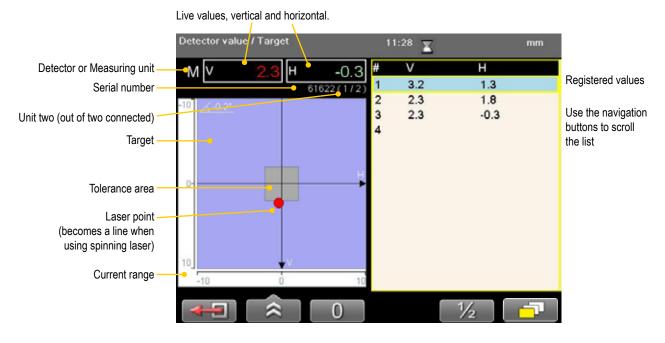
Measure roll parallity using an angle detector and a precision level.

PROGRAM VALUES



With the program Values, you can see live readings from the detectors. As default, a target and a table is displayed.

Press OK to register values.



Function buttons

	Back, leave program.
	See "Control panel" on page 15.
	See "Tolerance" on page 26.
	See "Zoom" on page 26.
	Save file. See "Measurement file handling" on page 11.
	See "Automatic recording" on page 28.
	Delete registered values.
	Print report on thermal printer (optional equipment).
	See "Streaming values" on page 29.
0	Set current value to zero.
1/2	Halve displayed value.
1/1	Return to absolute value.
	Only available after zeroing or halving.
	Choose how to display values. Use left and right navigation button to switch between two or more detectors when only one target is displayed.

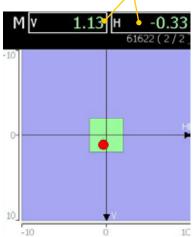


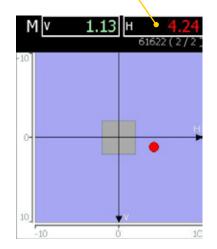
1. Select and to set tolerance. It is possible to set different tolerance in vertical and horizontal direction.

- 2. Use navigation buttons to move between the fields and to change the tolerance.
- 3. Press OK.

Live values and marking displayed in green when within tolerance.

Live values displayed in red when outside tolerance.





Zoom



2. Select a zoom factor between 1–5. Use navigation buttons to increase or decrease zoom factor.



Select tolerance. Press OK to save.

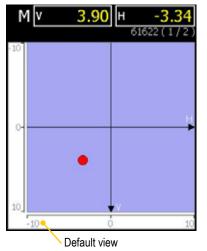
2

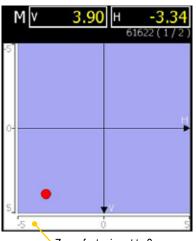
Horizontal

2

Tolerance - mm Vertical

3. Press OK.



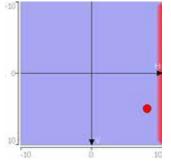


Zoom factor is set to 2

0-

Edge warning

When the laser beam is close to the edge, the edge is "lit up" as a warning. It is not possible to register values when you see the edge warning.



Halve or Zero set value

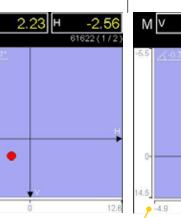
Halve value Select 22 to half displayed value. Zero point of the PSD moves halfway towards the laser point.

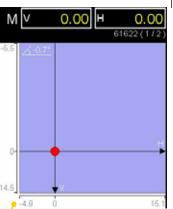
ΜV

7.4

Zero set value

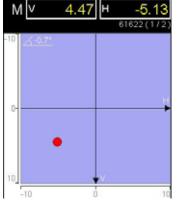
Select 0 to zero set displayed value. Zero point of the PSD moves to the laser point.





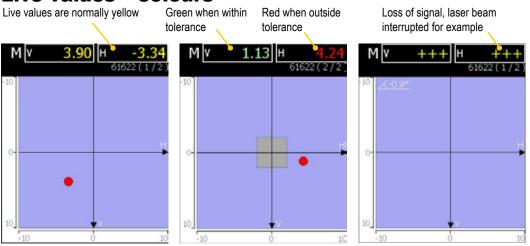
Absolute value

Select to return to the absolute value. Zero point of the PSD returns to the PSD centre.



Note the change of the current range

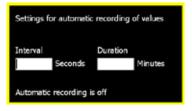
Live values - colours



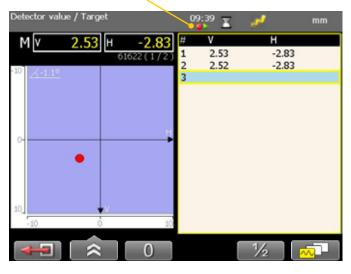
Automatic recording

In Values, it is possible to make automatic recording of values. This is very useful when you want to register values during a longer time period for example.

- 1. Select and to start automatic recording.
- 2. Set Interval.
- 3. Press navigation button "right".
- 4. Set Duration.
- 5. Press **OK**. The recording will start and you can follow the progress on screen.



Icon indicates that values are being recorded



Views

You can decide how to display the current values. As default a target and a table is displayed, but you can choose to show only target for example.

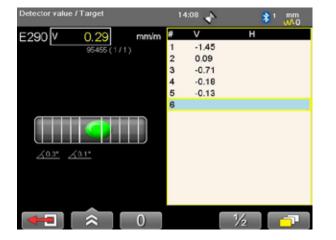
Select **with a select in the select select in the select in the select select in the select s**

Note!

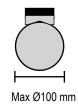
Use left and right navigation button to switch between two or more detectors when only one target is displayed.

Precision level E290

Connect the Precision level via Bluetooth, see *"Bluetooth*® set up" on page 21. For calibration, see *"Precision level E290" on page 148.*



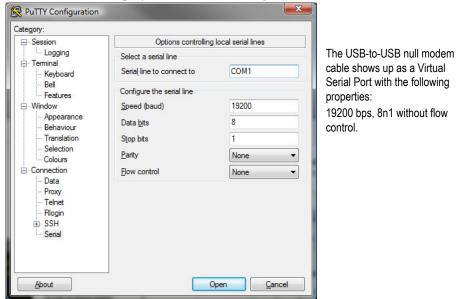
When measuring a shaft using the Precision level, we recommend that the shaft is no larger than 100 mm in diameter.



Streaming values

With the Streaming value functionality, you can transfer data from the Display unit. For this to work, you need a USB to USB Null Modem Cable, the USB cable delivered with the system does not work for streaming values.

1. Connect the Display unit to the PC using a USB to USB Null Modem Cable.



The port number can, for example, be found using the Device Manager. See 'USB Serial Port' under 'Ports (COM and LPT)'.

- 2. Click Open.
- 3. Start the program Values in the Display unit.
- 4. Select and if and to start streaming values.
- 5. To stop, select

P COM7 - PUTTY	0.0.4
5:62737:1:-2.62:1.7:1000000.0:-0:-0.7: M:6623:2.02:-3.63:-179.7:1000000.0:0.7: 5:62737:1.2.62:1.6:1000000.0:0.1: N:61621:2.02:-3.63:-179.6:1000000.0:0.7: 5:62737:1.01:-2.62:1.9:1000000.0:0.1: M:61621:2.02:-3.63:-179.6:1000000.0:0.7: 5:62737:1.01:-2.62:2.0:1000000.0:0.1: M:61621:2.02:-3.63:-179.5:1000000.0:0.7: 5:62737:1.01:-2.62:1.9:1000000.0:0.1: M:61621:2.02:-3.63:-179.5:1000000.0:0.4: 5:62737:1.01:-2.62:1.6:1000000.0:0.4: 5:62737:1.01:-2.62:1.8:1000000.0:0.6: M:61621:2.02:-3.63:-179.7:10000000.0:0.6: 5:62737:1.01:-2.62:1.8:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.62:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:1.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:1000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:62737:0.01:-2.63:1.9:000000.0:0.6: 5:6273:0.01:-2.63:1.0:000000.0:0.6: 5:6273:0.01:	In is st
5;42737;1;-2;41;;,7:1000000,0;0,0;0 M;61631;2:01;-3:83;-179;5:1000000,0;0,6; 5;62737;1;-2;41;1:7;1000000,0;0;0;0;	

In this example, PuTTY is used to show the streamed data

Data format

The data is sent as lines with semi colon separated values. Each line begin with a detector identification, S, M, Vib or BTA, followed by the detector serial number. The unit and resolution depends on the settings in the user profile.

Data from Vib: Vib;serial;LP;HP;G;

Data from BTA: BTA;serial;PSD1X;PDF2X;PDF3X;X axis angle;Y axis angle;Z axis angle;

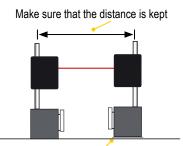
Data from S: S;serial;PSD X; PSD Y; X axis angle;Y axis angle;Z axis angle; **Data from M:** M;serial;PSD X; PSD Y; X axis angle;Y axis angle;Z axis angle;

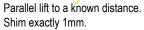
Calibration check

Use the program Values to check if the detector readings are within specified tolerances.

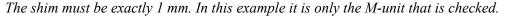
Quick check

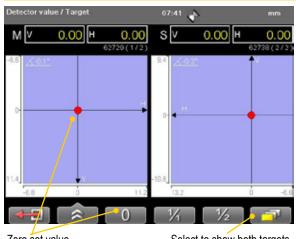
- 1. Set the tolerance to 0.01 mm (0.5mil).
- 2. Select **and** show targets for both M- and S-unit.
- 3. Select 0 to zero set value.
- Place a shim under the magnet base to lift the M-unit 1mm (100mils). The M-unit's reading shall correspond to the movement within 1% (1mil ± 1digit) (0.01mm ± 1 digit).
- 5. Remove the shim from the M-unit.
- 6. Select 0 to zero set value.
- 7. Make a mark to mark out the position of the detector.
- Place the shim under the magnet base of the S-unit. The S-unit's reading shall correspond to the movement within 1% (1mil ± 1digit) (0.01mm ± 1 digit).





Note!



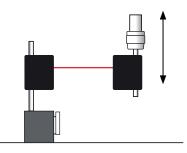


Zero set value

Select to show both targets.

Precision check

- 1. Fasten one unit in a machine tool.
- 2. Select 0 to zero set value.
- 3. Move the units a known distance is to use the movement of a machine tool spindle.
- 4. The fastened unit's reading shall correspond to the movement within 1% (1mil ± 1digit) (0.01mm ± 1 digit).



Note!

In this example it is only the unit fastened in the machine that is checked.

HORIZONTAL



For horizontally mounted machines.

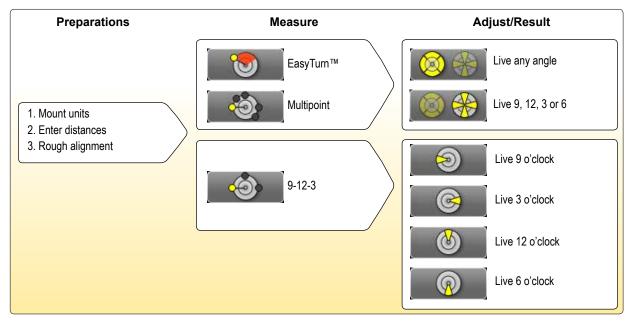
Select between three different measuring methods:

0	EasyTurn [™] Start anywhere on the turn. The three measuring positions can be reg- istered with as little as 20° between positions. By default, the EasyTurn program is shown. See "Measure using Easy Turn [™] " on page 35.
-@	Horizontal Multipoint Start anywhere on the turn. Register as many points as you wish. See "Thermal compensation" on page 42
-39	9-12-3The measuring positions are registered at positions 9, 12, 3 o'clock. The inclinometers are not used.<i>"Measure using 9-12-3" on page 38.</i>

Note!

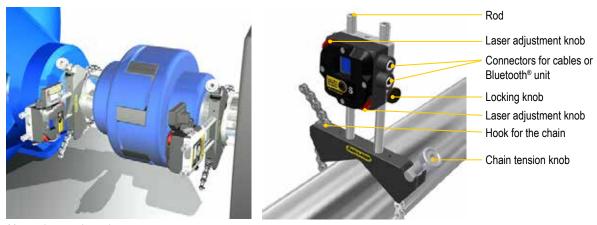
Measurements made with older versions of the Horizontal program are opened with the older version of the program. For information regarding the previous program version, please see corresponding manual.

Work flow



Mount the units

- 1. Mount the S-unit on the stationary machine and the M-unit on the movable machine.
- 2. Mount the units facing each other. Make sure they are at the approximately same rotational angle and radius.



Mounted measuring units

Connect cables or Bluetooth® units

Cable

The measuring units has two connectors that are used for cables or Bluetooth® units.

- 1. Connect a cable to the Display unit. Connect the other end to any of the measuring units.
- 2. Connect the second cable between the measuring units.

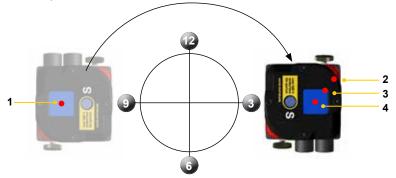
Bluetooth[®]

The Display unit is equipped with Bluetooth[®] wireless technology, which makes it possible for the Display unit to receive data without using cables. For more information, see *"Bluetooth*[®] set up" on page 21.

Adjust measuring units

When making a new installation, a rough alignment can be necessary. Place the Measuring units on the rods, make sure they are at the approximately same rotational angle and radius. Also make sure that the adjustment knob is adjustable in both directions.

- 1. Place the Measuring units at 9 o'clock. Aim the laser beams at the centre of the targets.
- 2. Turn the shaft to position 3 o'clock. Note where the laser beams hit.
- 3. Adjust the laser beams half way to the centre of targets. Use the adjustment knobs.
- 4. Adjust the movable machine until the laser beam hits the centre of targets.

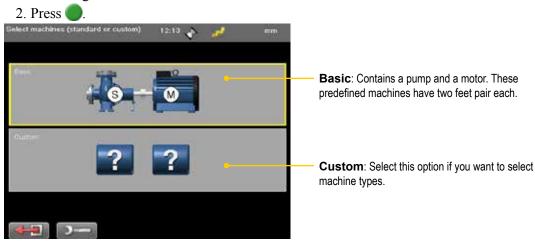


The example shows the S-unit, but the procedure is made on both units.

Select machines

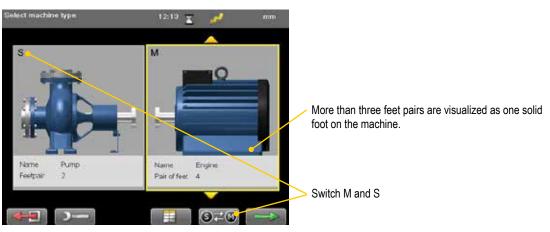
Before measuring your machines, you need to define what kind of machines you have.

1. Use navigation buttons to select Basic or Custom.



Custom

Select this option if you want to select machine types. There are several machine types to choose from. You can also define as many feet pairs as you need on the machines.



- 1. Use navigation buttons up and down to find the machine you want.
- 2. Press . The next machine becomes active.

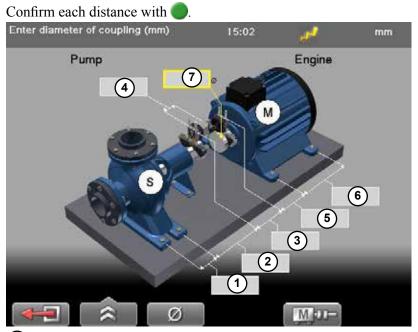
When you are done, select **when you are done**, select **whe**

Select number of feet pair

If you want to change the number of feet pair on the machine, simply enter the number you want on the numerical buttons.

	Leave program.
)—	See "Control panel" on page 15.
	Open table to rename the machines and change the number of feet pairs.
Ø ₊` 6	Switch on which machine you will place the S (stationary) and M (movable) measuring unit.
\rightarrow	Continue to Measure view.

Enter distances



(1) Distance between first and second feet pair. Optional, select is to activate field.

(2) Distance between second feet pair and S-unit. Optional, select is to activate field.

- (3) Distance between S-unit and M-unit. Measure between the rods.
- (4) Distance between S-unit and centre of coupling.
- (5) Distance between M-unit and feet pair one.
- (6) Distance between feet pair one and feet pair two.
- (7) Coupling diameter. Optional, select on activate field.

	Leave program.
	See "Control panel" on page 15.
	See "Tolerance" on page 44.
	See "Thermal compensation" on page 42.
	Select to enter distances of the S-machine.
	Toggle between showing Distance view in 3D or 2D.
Ø	Diameter . Select to enter coupling diameter. This is necessary if you want the result based on the gap of the coupling instead of angle.
M M	Toggle button. Show movable machine to the left or the right.
	Continue to Measure view. Available when you have entered the manda- tory distances.

Measure using Easy Turn™

Preparations

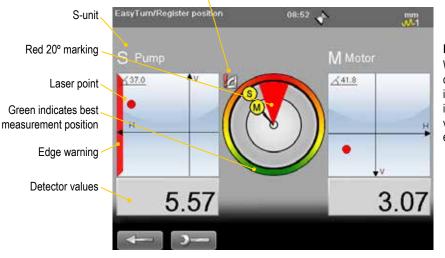
Follow the preparations as described in the previous pages.

- 1. Mount the measuring units.
- 2. Enter distances, confirm each distance with **O**.
- 3. If needed, perform a rough alignment.
- 4. If needed, perform a Softfoot check.

Measure

It is possible to measure with as little as 40° spread between the measurement points. However, for an even more accurate result, try to spread the points as much as possible. The colours indicates where the optimum positions to measure are.

- 1. Adjust laser to the centre of the targets. If needed, adjust the units on the rods, then use laser adjustments knobs.
- 2. Press to register first position. The first position is automatically set to zero. A red marking is displayed.
- 3. Turn shafts outside of the red 20° marking.
- 4. Press b to register second position.
- 5. Turn shafts outside of the red markings.
- 6. Press **o** to register third position. The Result and adjust view displayed. Angle warning. Shown if the angle between M and S is greater than 2 degrees.



Edge warning

When the laser beam is close to the edge, the edge is "lit up" as a warning. It is not possible to register values when you see the edge warning.

	Back. Measure previous position or back to Distance view.
)—	See "Control panel" on page 15.
Ö	Switch to the EasyTurn™ method. Switch to the 9-12-3 method. Switch to the Horizontal Multipoint method.
O.	See "SOFTFOOT" on page 47.

Measure using Multipoint

Preparations

Follow the preparations as described in the previous pages.

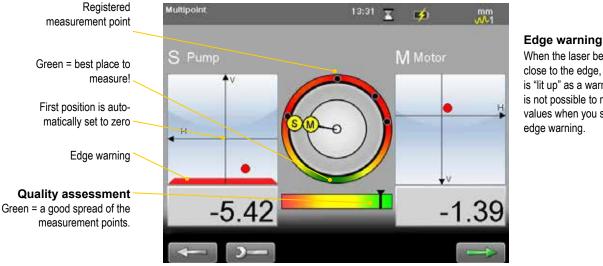
- 1. Mount the measuring units.
- 2. Enter distances, confirm each distance with .
- 3. If needed, perform a rough alignment.
- 4. If needed, perform a Softfoot check.

Measure

- 1. Select **and and to** switch to Horizontal Multipoint.
- 2. Adjust laser to the centre of the targets. If needed, adjust the units on the rods, then use laser adjustments knobs.
- 3. Press on to register first position. The first position is automatically set to zero.
- 4. Press **()** to register as many points as you wish. After three points a result is available.
- 5. Select **content** to display the Result and adjust view. See *"Result and adjust" on page* 39.

Spread the measurement points

For a more accurate result, try to spread the points as much as possible. The colours indicates where the optimum positions to measure are. The colour bar indicates a statistical accuracy of the measurement.



When the laser beam is close to the edge, the edge is "lit up" as a warning. It is not possible to register values when you see the edge warning.

	Back. Measure previous position or back to Distance view.
) —	See "Control panel" on page 15.
0	Switch to the EasyTurn [™] method. Switch to the 9-12-3 method. Switch to the Horizontal Multipoint method.
9	See "SOFTFOOT" on page 47.
	Continue to the Result and adjust view. Available after registering three positions with a minimum spread of 40°.

Quality assessment

Not available for the US market!

From the result view, select and interview to show the Quality assessment view

Attainable accuracy

Many measurement points that also have a good spread, will statistically ensure a high accuracy. This is the same indicator as on the measurement view. If the attainable accuracy is low, try to spread the points as much as possible.

Acquired accuracy

Actual measured values from the units. If the acquired accuracy is low, it may depend on for example air turbulence or bearing clearance.

Temperature stability

Measured temperature variation in the measuring units. If the stability is low, remeasure when the temperature has stabilized.

Measurement direction

Indicates if you have changed measurement direction. It is better to move the measurement units in the same direction.

Quality assessment

A sum of the four quality factors. Also available in the pdf report.

Quality Assessment	08:47 🔶	
Number of cointsi 5 Temperature drift M-unit: ±0,1 °C S-unit: ±0,1 °C	Attainable accuracy Acquired accuracy Temperature stability Measurement direction	
	Quality	-

Measure using 9-12-3

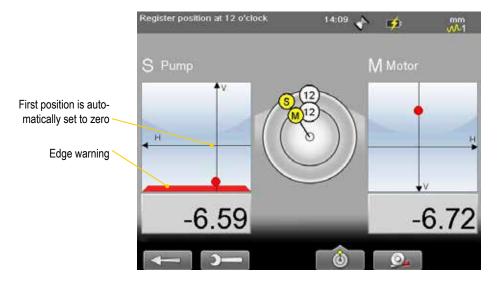
Preparations

Follow the preparations as described in the previous pages.

- 1. Mount the measuring units.
- 2. Enter distances, confirm each distance with **O**.
- 3. If needed, perform a rough alignment.
- 4. If needed, perform a Softfoot check.

Measure

- 1. Select and to switch to 9-12-3.
- 2. Adjust laser to the centre of the targets. If needed, adjust the units on the rods, then use laser adjustments knobs.
- 3. Turn shafts to 9 o'clock.
- 4. Press on to register first position. The first position is automatically set to zero.
- 5. Turn shafts to 12 o'clock.
- 6. Press on to register second position.
- 7. Turn shafts to 3 o'clock.
- 8. Press () to register third position. The Result and adjust view is displayed. See *"Result and adjust" on page 39.*



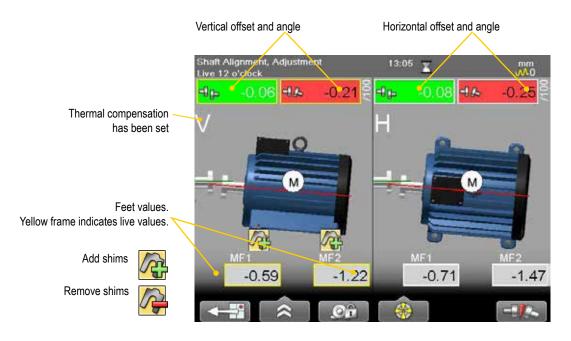
Edge warning

When the laser beam is close to the edge, the edge is "lit up" as a warning. It is not possible to register values when you see the edge warning.

	Back. Measure previous position or back to Distance view.
) —	See "Control panel" on page 15.
ů I	Switch to the EasyTurn [™] method. Switch to the 9-12-3 method. Switch to the Horizontal Multipoint method.
<u>_</u>	See "SOFTFOOT" on page 47.

Result and adjust

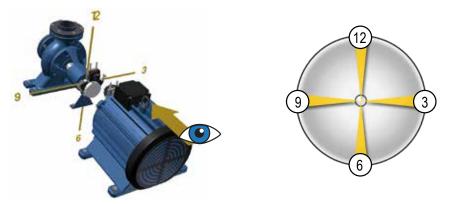
Offset, angle and feet values are clearly displayed. Both horizontal and vertical direction are shown live, which makes it easy to adjust the machine. Values within tolerance are green.



	Back to measure view.
	See "Control panel" on page 15.
	Save, see "Measurement file handling" on page 11.
	See "Tolerance" on page 44.
	See "Thermal compensation" on page 42.
	Show target. This is a quick way to see where the laser beam hits the target and how the measuring units are positioned.
	Print report on thermal printer (optional equipment). Available when you open a saved measurement.
	Edit distances . Press t o confirm changes. The result is recalculated. See " <i>Quality assessment</i> " on page 37.
.Oô	RefLock, lock feet. Note! Not available for E420.
*	See "Live values" on page 40. Toggle button. Show/hide Position indicator. See "Position indicator" on page 41.
/100	Toggle button. Switch between to show gap and show angular error per 100 mm. For this to work you need to set the coupling diameter.

Live values

When reading the values, face the stationary machine from the movable machine. Positions for measuring units as seen from the movable machine. Live values are marked with yellow frame.

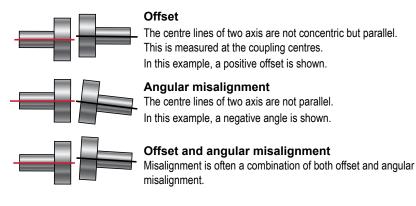


Face the stationary machine (S) from the movable machine (M). Then 9 o'clock is to the left, as in the measuring programs.

Offset and angle values

The offset and angle value indicate how well the machine is aligned at the coupling. They appear in both horizontal and vertical direction.

These values are important to get within tolerance.



Show live values for EasyTurn[™] and Multipoint

The inclinometer can be used to show live values at all angles.



Show live values at any angle.

Inclinometer controls when to show live values.

Show live values for 9-12-3

The inclinometer is not used. You can manually show in which position your measurement units are.

Select show the live options.

@	Force live to 6 o'clock.
6	Force live to 12 o'clock.
C	Force live to 3 o'clock.
9	Force live to 9 o'clock.

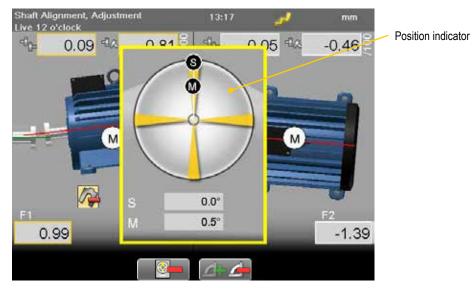
Adjust

Adjust the machine if needed.

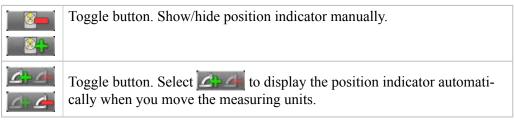
- 1. Shim the machine according to the vertical feet values.
- 2. Adjust the machine sideways according to the live horizontal values.
- 3. Tighten the feet.
- 4. Select to remeasure.

Position indicator

To adjust, you need to place the measuring units in live position (9, 12, 3 or 6 o'clock). Select to show the Position indicator.



Function buttons



Save

You can save a measurement and open it later to continue to measure. When you save the measurement again, it will **not** overwrite the earlier version.

When you save a measurement, a pdf is automatically generated.

See "Measurement file handling" on page 11.

Thermal compensation

During normal operation, machinery is influenced of different factors and forces. The most common of these changes is the change in the temperature of the machine. This will cause the height of the shaft to increase. This is called thermal growth. To compensate for thermal growth, you enter values for cold condition compensation.

Select and from the result and distance view. The Thermal compensation view is displayed.

Example

2

3

It can be necessary to place the cold machine a bit lower to allow thermal growth. In this example we assume a thermal growth of +5mm in **HOT** condition. Therefore we compensate with -5mm in **COLD** condition.

1 Before thermal compensation.

Set thermal compensation.

Indicates that the compensation values are set for cold (offline) condition.

Vertical offset and angle for movable machine.

Thermal compensation set. When you have set thermal compensation and return to the result view, the values have changed. When the machine becomes warm, the thermal growth will make it perfectly aligned.

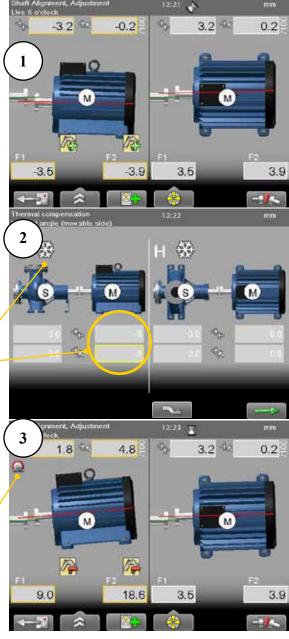
Indicates that thermal compensation has been set

Feet values

- 1. On the distance view, enter distances for the S-machine.
- 2. Select
- 3. Set thermal compensation values based on feet values. The coupling values are recalcalculated. If there are more than two feet pairs, you enter values for the first and last feet pair.

Note!

Only the coupling values are visible in the PDF report and the printed report.

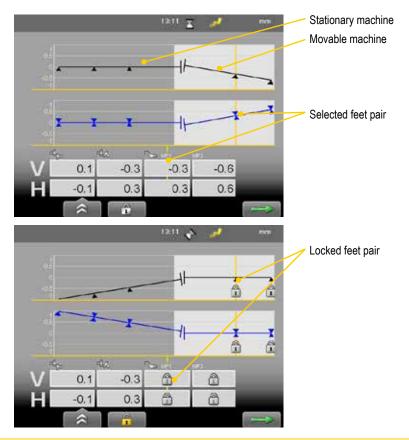




RefLock™

From the result view, you can select the function RefLock[™]. Here you can choose any two feet pairs as locked and thus choose which machine is to be used as stationary and which as adjustable. If you want to lock feet pair on the stationary machine, you need to enter distances.

- 1. Select and Of
- 2. The RefLock graph view is displayed. Navigate using the left and right navigation button.
- 3. Select **1** to lock the selected feet pair or **1** to unlock.
- 4. Select to continue to the result view.



Note!

RefLock[™] is available when using the program Horizontal. Not available for programs Vertical or Cardan.

Tolerance

1. Select and . The tolerance window is displayed.

	erance	14:13 置		mm			
				Select coupling tole	rance	14:12	S
upling S-M	RPM	Offset	Angula				
nent tolerance	No tolerance		•	Coupling S-M	RPM	Offset	Angular error
0.03/40	0-1000	0.09	0.04/40		No tolerance		
0.03040	1000-2000	0.07	0.03/40	-MB U.U/	0-1000	0.09	0.09/100
	2000-3000 3000-4000	0.05	0.02/40	9/2 0.07/100	1000-2000	0.07	0.07/100
	4000-	0.03	0.00/40		2000-3000	0.05	0.05/100
	Add new tolerance	0.01	0.001+0		3000-4000	0.03	0.03/100
	Add new tolerant.e				4000-∞	0.01	0.01/100
	·				Add new toleran:	e	
					/	_	
	Concession in the local division in the loca			/			

Add user defined tolerance

Function buttons

-	Close Tolerance view.
)—	See "Control panel" on page 15.
	Edit user defined tolerance.
Ē	Delete user defined tolerance.

Add new tolerance

You can add your own user defined tolerance.

- 1. Select the row "Add new tolerance". Press 🥘.
- 2. Enter name and tolerance.
- 3. Press . The new tolerance is added to the list.

Tolerance in result views

The tolerances are clearly displayed in the result views.

Green = within tolerance

Red = not within tolerance



Tolerance table

The rotation speed of the shafts will decide the demands on the alignment. The table on this side can be used as a guidance if no other tolerances is recommended by the manufacturer of the machines.

The tolerances is set to the maximum allowed deviation from accurate values, with no consideration to if that value should be zero or compensated for thermal growth.

	Excellent		Acceptabl	Acceptable		
rpm	mils	mm	mils	mm		
0000-1000	3.0	0.07	5.0	0.13		
1000-2000	2.0	0.05	4.0	0.10		
2000-3000	1.5	0.03	3.0	0.07		
3000-4000	1.0	0.02	2.0	0.04		
4000-5000	0.5	0.01	1.5	0.03		
5000-6000	<0.5	< 0.01	<1.5	< 0.03		

Offset misalignment

Angular misalignment

	Excellent		Acceptable		
rpm	mils/"	mm/100mm	mils/"	mm/100mm	
0000-1000	0.6	0.06	1.0	0.10	
1000-2000	0.5	0.05	0.8	0.08	
2000-3000	0.4	0.04	0.7	0.07	
3000-4000	0.3	0.03	0.6	0.06	
4000-5000	0.2	0.02	0.5	0.05	
5000-6000	0.1	0.01	0.4	0.04	

The higher the rpm of a machinery is, the tighter the tolerance must be. The acceptable tolerance is used for re-alignments on non-critical machinery. New installations and critical machines should always be aligned within the excellent tolerance.

Note!

Consider these tables as guidelines. Many machines must be aligned very accurately even if they have a lower rpm. For example gearboxes.

Horizontal





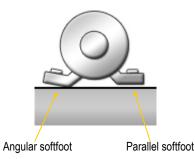
Perform a softfoot check to ensure that the machine is resting evenly on all its feet. A softfoot can be angular and/or parallel, see image.

Softfoot can be caused by:

- Twisted machinery foundations.
- Twisted or damaged machinery feet.
- Improper amount of shims under machine feet.
- Dirt or other unwanted materials under machine feet.

Start Softfoot from main shaft menu

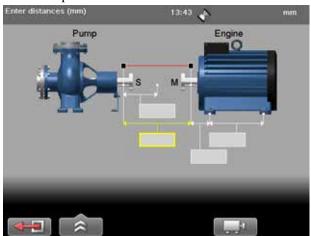
- 1. Select 🖳 and 🔍.
- 2. Enter distances. Select "Custom" if you want to select other machine images and/or more than three feet pair.



3. Select **I** to continue.

Start Softfoot from Horizontal program

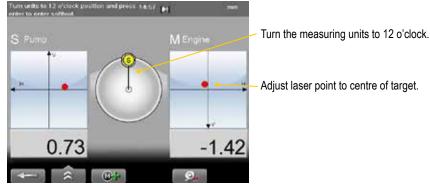
- 1. Select **III**, and **III** to open Horizontal program.
- 2. Enter distances. Confirm each distance with **OK**. To perform a Softfoot check, you need to enter distances between the feet pairs. The measure view is displayed.
- 3. Select Softfoot is only available before you have registered any measurement points.



	Leave program.
*	See "Control panel" on page 15.
	Enter distance for S-machine. Makes it possible to perform a soft-
	foot measurement on the S-machine.
	Toggle between 3D and 2D view.
1213	Add a feet pair. Only available for E530. In E710 you select machines and optional number of feet when you select custom.
M	Toggle button. Show movable machine to the left or the right.
	Continue to Measure view. Available when you have entered the distances.

Measure softfoot

- 1. Tighten all feet bolts.
- 2. Turn the measuring units to 12 o'clock.
- 3. Adjust laser to the centre of targets. If needed, adjust the units on the rods, then use laser adjustments knobs.



- 4. Press OK. The Softfoot measure view is displayed. The first bolt is marked with yellow.
- 5. Loosen and then retighten the first bolt.
- 6. Press OK to register value.
- 7. Register values on all four feet. The result is displayed.
- 8. Shim the foot with the largest movement.
- 9. Do a Softfoot check again.

Measure:

Result:

nai 🎝

Loosen and retighten bolt before register value. Arrow indicating that the machine is tilting in this direction.



Note!

If the largest movement is opposite from the smallest it is not a conventional softfoot and you will be asked to check the foundation.

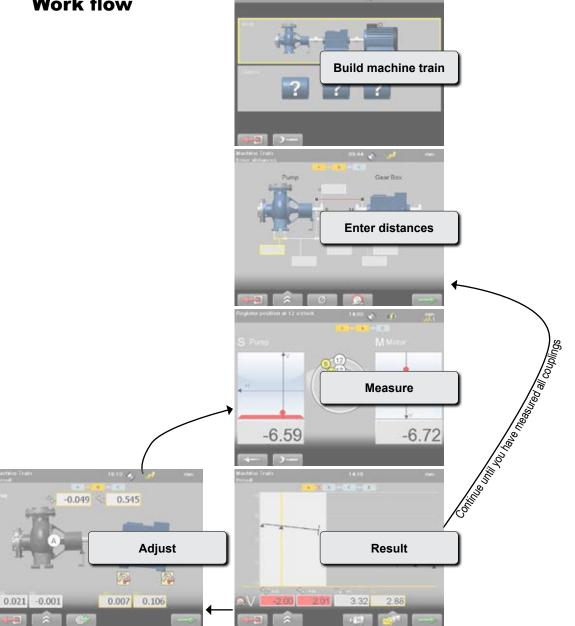
-	Leave Softfoot.
Â	See "Control panel" on page 15. Save. Only available when you have started Softfoot from the main menu.
~ 0	Zero value of selected foot.
	Toggle button to switch machine. To check Softfoot, distances between feet pairs are necessary. If needed, the Enter distance view is displayed. <i>Not available for E420</i> .
←	Remeasure Softfoot.
	Continue to Measure view, only available when you have started Softfoot from the program Horizontal.

MACHINE TRAIN

-11- -11-

Use for machines mounted in a train with two or more couplings.

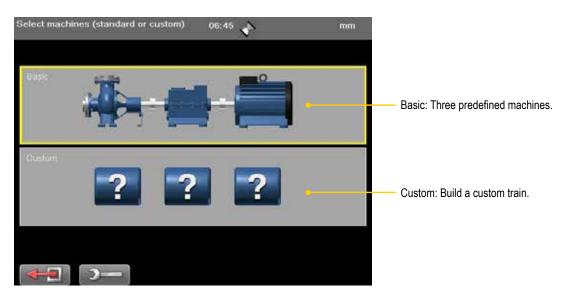
Work flow



Build machine train

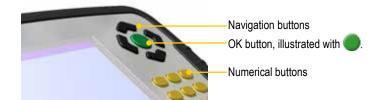
Before measuring your machines, you need to define what kind of machines you have.

- 1. Use navigation buttons to select Basic or Custom.
- 2. Press O.



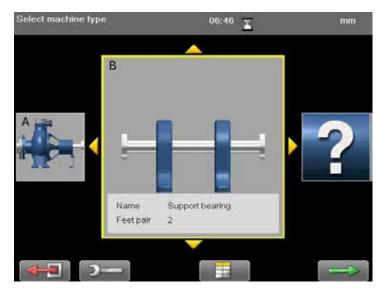
Basic

The basic machine train contains a pump, a gearbox and a motor. These three predefined machines all have two feet pair each.



Custom

Select this option if you want to build a custom machine train. You build the train from left to right. There are several machine types to choose from and you can add as many as you need to your machine train. You can also define as many feet pairs as you need on the machines.

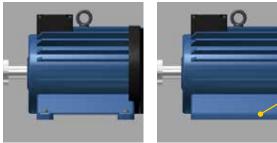


Select machine

- 1. Use navigation buttons up and down to find the machine you want.
- 2. Press . The next machine becomes active.
- 3. Add as many machines as you need. When you are done, select **continue** to Continue to Measure view.

Select number of feet pair

If you want to change the number of feet pair on the machine, simply enter the number you want on the numerical buttons.

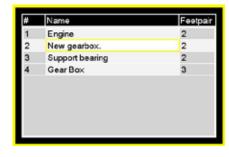


More than three feet pairs are visualized as one solid foot on the machine.

Machine with two feet pairs

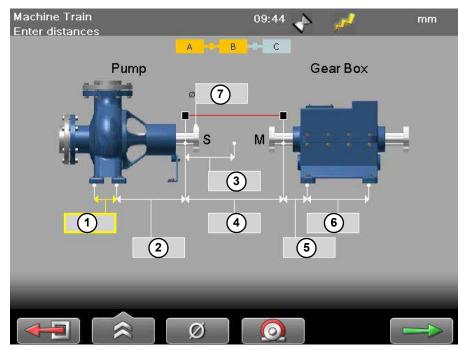
Build train table

Select to open a table view. In this table you can rename the machines and change the number of feet pairs.



Enter distances

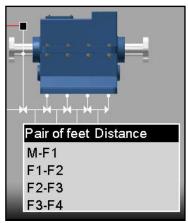
Confirm each distance with **O**.



- 1 Distance between first and second feet pair.
- (2) Distance between second feet pair and S-unit.
- Distance between S-unit and centre of coupling.
- (4) Distance between S-unit and M-unit. Measure between the rods.
- 5 Distance between M-unit and feet pair one.
- 6 Distance between feet pair one and feet pair two.
- (7) Coupling diameter. Optional, select _____ to activate field.

Function buttons

	Leave program.
	See "Control panel" on page 15.
	See "Thermal compensation" on page 42.
Ø	Diameter . Select to enter coupling diameter. This is necessary if you want the result based on the gap of the coupling instead of angle.
	Continue to Measure view.



When there are more than three feet pairs, a table is displayed where you enter the distances.

Measure using EasyTurn™

It is possible to measure with as little as 40° spread between the measurement points. However, for an even more accurate result, try to spread the points as much as possible. The colours indicates where the optimum positions to measure are.

- 1. Adjust laser to the centre of the targets. If needed, adjust the units on the rods, then use laser adjustments knobs.
- 2. Press **o** to register first position. The first position is automatically set to zero. A red marking is displayed.
- 3. Turn shafts outside of the red 20° marking.
- 4. Press b to register second position.
- 5. Turn shafts outside of the red markings.
- 6. Press on to register third position. The Result and adjust view displayed.
- 7. The result is displayed. You can show the result as graph, table or machine view. *See chapter Result.*
- 8. From the result view, select **weak** to measure next coupling. If you want to adjust the coupling, select the machine you want to adjust and press **.** *See chapter Adjust*.

greater than 2 degrees. syTurn/Register p S-unit 08:52 3 M-1 C. Red 20° marking M Motor ×41.8 (37.0 Laser point Green indicates best measurement position Edge warning Detector values 3.07 5.57

Angle warning. Shown if the angle between M and S is

Edge warning

When the laser beam is close to the edge, the edge is "lit up" as a warning. It is not possible to register values when you see the edge warning.

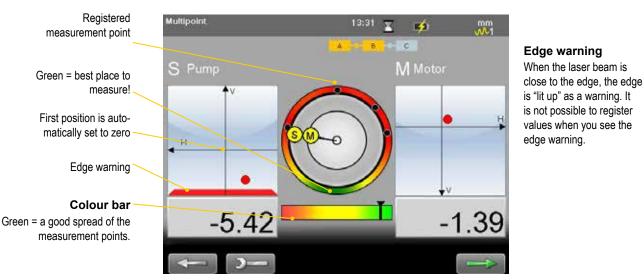
	Back. Measure previous position or back to Distance view.
) –(See "Control panel" on page 15.
Ö	Switch to the EasyTurn™ method. Switch to the 9-12-3 method. Switch to the Horizontal Multipoint method.
<u>_</u>	See "SOFTFOOT" on page 47.

Measure using Multipoint

- 1. Select and to switch to Horizontal Multipoint.
- 2. Adjust laser to the centre of the targets. If needed, adjust the units on the rods, then use laser adjustments knobs.
- 3. Press on to register first position. The first position is automatically set to zero.
- 4. Press () to register as many points as you wish. After three points a result is available.
- 5. Select **select** to display the Result and adjust view. You can show the result as graph, table or machine view. *See "Result" on page 56.*
- 6. From the result view, select **weak** to measure next coupling. If you want to adjust the coupling, select the machine you want to adjust and press . *See "Adjust" on page 60*.

Spread the measurement points

For a more accurate result, try to spread the points as much as possible. The colours indicates where the optimum positions to measure are. The colour bar indicates how statistical accurate the measurement is.



	Back. Measure previous position or back to Distance view.
)—	See "Control panel" on page 15.
6	Switch to the EasyTurn TM method. Switch to the 9-12-3 method. Switch to the Horizontal Multipoint method.
9	See "SOFTFOOT" on page 47.
	Continue to the Result and adjust view. Available after registering three positions.

Measure using 9-12-3

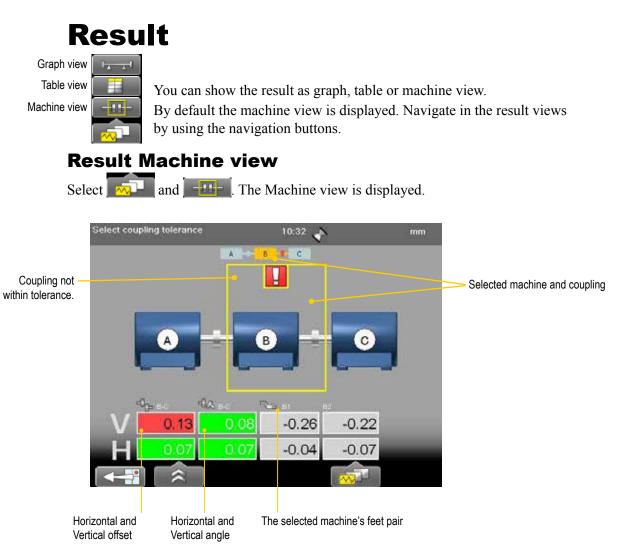
- 1. Select and to switch to 9-12-3.
- 2. Adjust laser to the centre of the targets. If needed, adjust the units on the rods, then use laser adjustments knobs.
- 3. Turn shafts to 9 o'clock.
- 4. Press on to register first position. The first position is automatically set to zero.
- 5. Turn shafts to 12 o'clock.
- 6. Press b to register second position.
- 7. Turn shafts to 3 o'clock.
- 8. Press on to register third position. X



Return to enter distances

- 9. The result is displayed. You can show the result as graph, table or machine view. *See "Result" on page 56.*
- 10. From the result view, select **select** to measure next coupling. If you want to adjust the coupling, select the machine you want to adjust and press **.** See "Adjust" on page 60.

	Back. Measure previous position or back to Distance view.
)	See "Control panel" on page 15.
ı Ö	Switch to the EasyTurn [™] method. Switch to the 9-12-3 method. Switch to the Horizontal Multipoint method.
Ø.	Softfoot.



Feet pair

If there are more than three feet pairs, values are only displayed for the first three pairs in this view. To view values for all feet pairs, switch to Table view.

Adjust coupling

Select the machine you want to adjust and press . See "Adjust" on page 60.

	Remeasure the coupling. Press and hold to leave program.
	See "Control panel" on page 15.
	Save file . "Measurement file handling" on page 11.
	See "Tolerance" on page 62.
	See "Thermal compensation" on page 42.
	View and edit distance.
	Print . "Measurement file handling" on page 11.
	Toggle button. Show Gap or Angle values.
~	Switch result view.
	Measure next coupling.

Result Table view

Select and . The Result Table view is displayed. Navigate using the navigation buttons.

Select coupling tolerance			10:33 📉 mm				 Selected coupling Selected meching 	
	_	A B	B I C				Selected machine	
Coupling	Salact cours	Hori	9.35					
A-B	⊲ ₀ , -0.75	Select coupling tolerance 19!				0:35	35 💉 mm	
B-C	0.13	A						
		Machine	F1	F1			2	
		Machine	н	V	н	v	2	
		A	0.07	0.00	-0.05	0.20		
		В	-0.04	-0.26	-0.07	-0.22		
		С	0.03	0.09	0.07	0.20		
Coupling val							_	
			_ ≈	Í		-1.5-	<u></u>	

Feet values

Function buttons

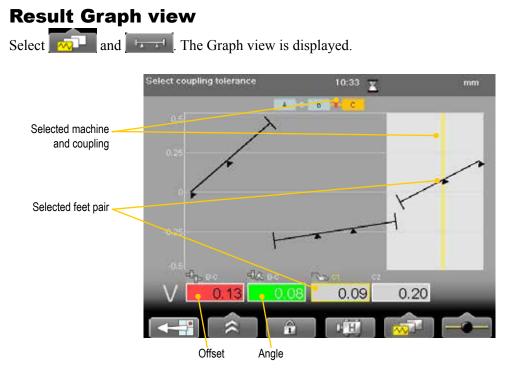
	Remeasure the coupling. Press and hold to leave program.
	See "Control panel" on page 15.
	Save file . "Measurement file handling" on page 11.
	See "Tolerance" on page 62.
	See "Thermal compensation" on page 42.
	View and edit distance.
	Print . "Measurement file handling" on page 11.
	Toggle button. Show Gap or Angle values.
a a a a a a a a a a a a a a a a a a a	Lock / unlock feet pair. Available when you show feet values. See "Lock feet pair" on page 59.
-194 -24	Toggle between showing feet or coupling values.
	Switch result view.

Save

You can save a measurement and open it later to continue to measure. When you save the measurement again, it will **not** overwrite the earlier version.

When you save a measurement, a pdf is automatically generated only when the whole train has been measured.

See "Measurement file handling" on page 11.



	Remeasure the coupling. Press and hold to leave program.
_ ≈ _	See "Result Machine view" on page 56.
	Lock / unlock feet pair. If you can not adjust a feet pair, use the lock function. <i>See "Lock feet pair" on page 59</i> .
HVH HVHH	Toggle between showing horizontal or vertical graph.
~	Switch result view.
	Available when you have measured the whole train. See "Best fit and Manual fit".
	Best fit
	Manual fit
	Select to measure next coupling.

Lock feet pair

This function is available in graph and table view. We recommend that you lock two feet pair to get the most accurate calculated reference line as possible. If you choose to lock only one feet pair, the tilt of the train is maintained and the coupling is offset.

Best fit and Manual fit

By default, an average best fit is calculated on the measured machine train. This means that the train is tilted to the flattest possible plane. If no feet pairs are locked, the system assumes that all machines are possible to move in all directions. For each coupling that you measure, the best fit is recalculated. When you have made adjustments on a coupling, the best fit is no longer recalculated.

Manual fit

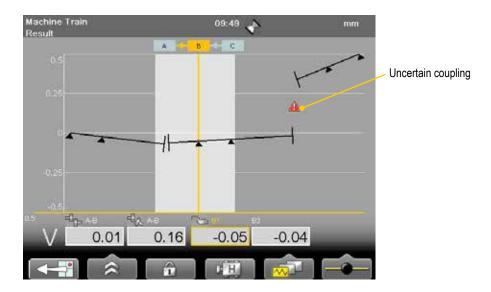
Only available when you have measured the whole train, and only in graph view. Use this function when you know that you for example can move a machine a little in one direction, but not at all in another direction.

- 1. Select and and to activate the Manual fit function. If there are locked feet pair, these are unlocked.
- 2. Use the numerical buttons to move the graph.
- Buttons 1 and 4 move the left part of the train
- Buttons 2 and 5 moves the whole train.
- Buttons 3 and 6 moves the right part of the train.
- Button -+ will change the scale.

To return to average best fit, select **and** and

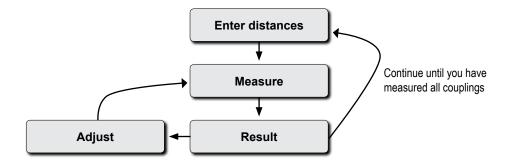
Uncertain coupling

When you adjust one coupling, it might affect the next coupling in the machine train. In the example below, the coupling A -B has been adjusted, which might have an affect on the coupling B - C. This is indicated with the symbol \triangle . When you remeasure or adjust the coupling, the warning is removed.

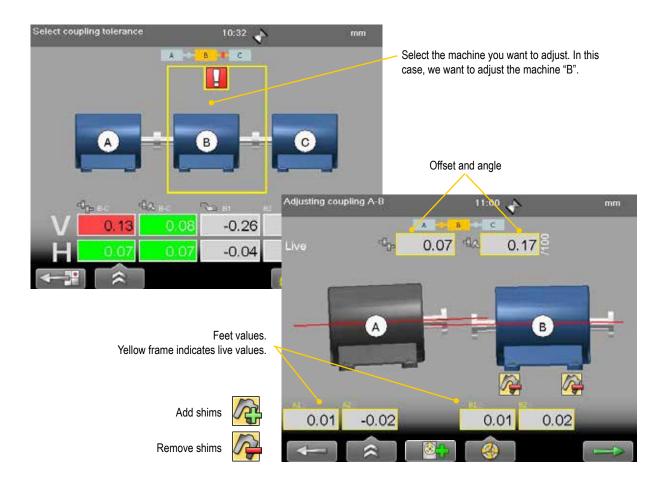


Adjust

You can adjust a machine even though you have not measured the whole train.



- Select the machine you want to adjust and press .
 If you just measured the coupling, the Adjustment view is displayed. If not, you need to remeasure the coupling first and the Measure view is displayed.
- 2. Adjust the machine.
- 3. Select when you are done. The Measure view is displayed.
- 4. Remeasure the coupling to confirm the adjustment.



Function buttons

	Back to result view. See "Control panel" on page 15.
<u>8</u> +- 8	Toggle button. Select to show/hide Position indicator. See "Position indicator" on page 41.
- 🛞 -	See "Live values" on page 40.
	Continue. You need to remeasure the coupling to confirm the position of the measuring units.

Uncertain coupling

When you adjust one coupling, it might affect the next coupling in the machine train. This is indicated with the symbol \triangle .

Scale

The scale of the graph might change when you have made adjustments.



Tolerance

- 1. Select and and The tolerance window is displayed.
- 2. Select a tolerance and press **()**. The next coupling in the train is selected.

	A	e c		Select coupling tole	rance	13:18 🔟	
Coupling A-B	RPM	Offset	Angula			e c	
	No tolerance	-		Coupling A-B	RPM	Offset	Angular error
	0-1000 1000-2000	0.09	0.09	Ourcent tolerance	No tolerance	-	. [
	2000-3000	0.07	0.07	⁼⁰ r= 0.07	0-1000	0.09	0.02/22
	3000-4000	0.03	0.03	🕂 0.02/22	1000-2000	0.07	0.02/22
	4000	0.03	0.03		2000-3000	0.05	0.01/22
	Add new tolerance		0.01		3000-4000	0.03	0.01/22
	Add new tolerance		-11		4000	0.01	0.00/22
	1				b	2.00	0.44/22
					d	2.00	0 44/22

GAP values

Function buttons

	Close Tolerance view.
)—	See "Control panel" on page 15.
	Edit user defined tolerance.
ā	Delete user defined tolerance.

Add new tolerance

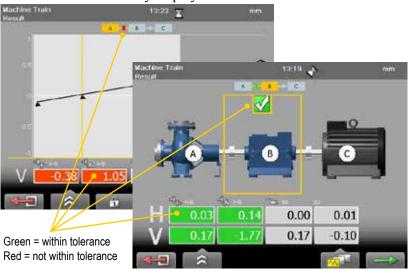
You can add your own user defined tolerance.

- 1. Select the row "Add new tolerance". Press 🥏.
- 2. Enter name and tolerance.
- 3. Press . The new tolerance is added to the list.

Tolerance in result views

The tolerances are clearly displayed in the result views.







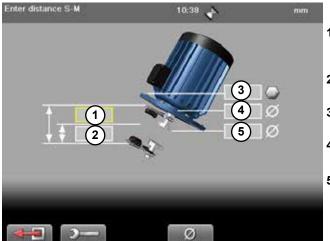


The program Vertical is used for vertical and/or flange mounted machines.

Preparations

- 1. Mount the M-unit on the movable machine and the S-unit on the stationary machine.
- 2. Select **III** and **I** to open Vertical program.
- 3. Enter distances. Confirm each distance with 🧶.

If you have a barcode reader, simply scan the barcode and all machine data is read. *See "Measurement file handling" on page 11.*



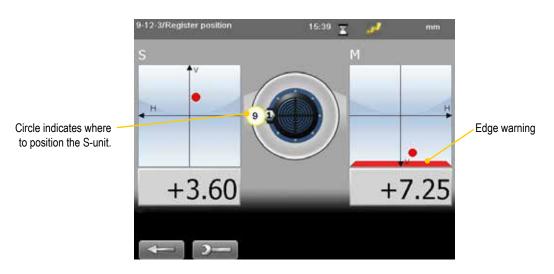
- 1 Distance between S-unit and M-unit. Measure between the rods. **Mandatory**.
- 2 Distance between S-unit and centre of coupling. Mandatory.
- **3** Number of bolts (4, 6 or 8 bolts).
- 4 Bolt circle diameter (centre of the bolts).
- **5** Coupling diameter. Select of activate field.

	Leave program.
)—	See "Control panel" on page 15.
Ø	Select to enter diameter of coupling.
\rightarrow	Forward to measure view.

Measure

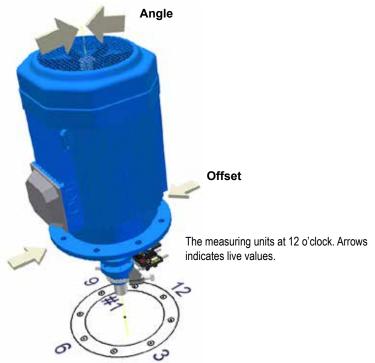
The program Vertical uses the 9-12-3 method.

- 1. Position the units at 9 o'clock, at bolt number one. Make sure that it is possible to also position the units at 12 and 3 o'clock.
- 2. Press on to register first position. The first position is automatically set to zero.
- 3. Turn units to position 12 o'clock.
- 4. Press **()** to register position.
- 5. Turn units to position 3 o'clock.
- 6. Press on to register position. Measurement result is displayed.



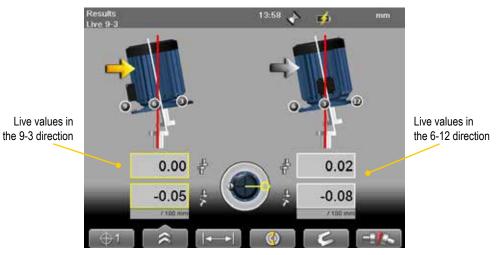
Edge warning

When the laser beam is close to the edge, the edge is "lit up" as a warning. It is not possible to register values when you see the edge warning.



Result

The result is displayed as sideways offset in the coupling and angular error between shafts.



Live values

The values can be displayed live in two directions:

- Live in the 9-3 direction.
- Select select and position the measuring units at 3 o'clock.
- Live in the 6-12 direction. Select and position the measuring units at 12 o'clock.

 1	Back, remeasure from first position.
_ ≈ _	See "Control panel" on page 15.
	Save, see "Measurement file handling" on page 11.
	Set tolerance.
	Show target . This is a quick way to see where the laser beam hits
	the target and how the measuring units are positioned.
	Print report on thermal printer (optional equipment). Only avail-
	able when you open a saved measurement.
↔	Adjust distances. Press on to confirm changes. The result is recalculated.
() ()	Toggle button. Switch between showing live values in the direction 9-3 or 6-12.
C	See "Shim result view" on page 66.
/100	Toggle button. Switch between to show gap and show angular error per 100 mm. For this to work you need to set the coupling diameter.

Shim result view

To view this, you need to enter number of bolts and diameter of bolt circle.



- 1. Select **c** to open Shim value view. The values are not live.
- 2. Read values. The highest bolt is calculated as 0.00. Values below zero indicates that the bolt is low and need shimming.
- 3. Select **Select** to return to Result view.

Note!

If you shim the machine, remeasure from position 9 o'clock to update all measurement values.

Adjust machine

- 1. Compare the offset and angular error to the tolerance demands.
- 2. If the angular error need to be adjusted, please shim the machine first, then adjust the offset.
- 3. Tighten the bolts and remeasure.

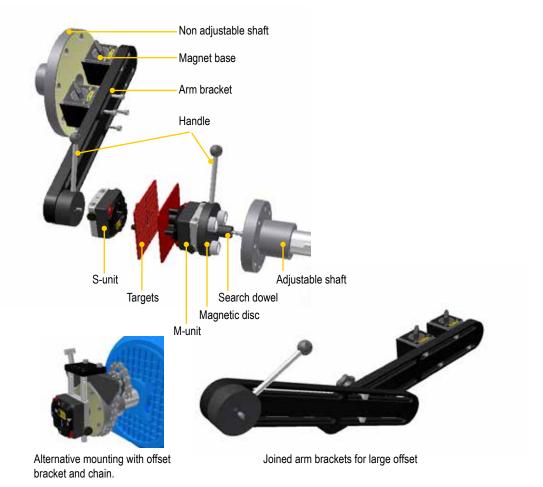




The Cardan program is used for alignment of cardan-shaft-coupled/centre-offset machines.

Mount the units

- 1. Mount the arm bracket on the non adjustable shaft. You can use the magnet bases or the mount the bracket directly on the flange.
- 2. Mount the S-unit on the arm bracket.
- 3. Mount the M-unit on the magnetic disc. If the adjustable shaft has a thread, use suitable search dowel. This makes the centering easier.
- 4. Mount the targets.



Enter distances

- 1. Select **III** and **III** to open Cardan program.
- 2. Enter distances. Confirm each distance with **OK**.



- 1 Distance between S-unit and M-unit. Measure between the rods. **Mandatory**.
- 2 Distance between feet pair one and feet pair two. Optional.

3 Coupling diameter. Optional, select moments to activate field.

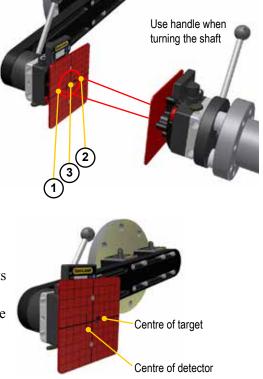
Function buttons

	Leave program.
)—	See "Control panel" on page 15.
Ø	Diameter . Select to enter coupling diameter. This is necessary if you want the result based on the gap of the coupling instead of angle.
\rightarrow	Continue . Available when you have entered the mandatory distances.

Cone laser beam

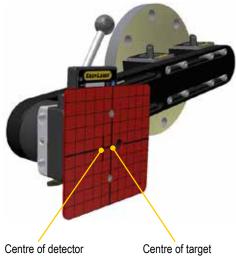
When you turn the shaft, the laser beam will draw a circle on the target. If the distance between S and M is small (<300 mm or 12 inch), it can be difficult to cone the laser beam. If this is the case, proceed to *Rough alignment*.

- 1. Note where the laser beam hit the target at position 1.
- 2. Turn one of the shafts 180°. Note the position 2.
- 3. Adjust the laser beam halfway towards position 1, to position 3.
- 4. Turn the shaft again. If the laser beam does not move when you turn, the laser beam is correctly coned.
- 5. Repeat step 2–5 with the opposite unit.
- 6. Position both units at 9 o'clock.
- 7. Move the arm bracket until the laser hits the centre of the target on the M-unit.
- 8. Adjust the S-unit laser beam until it hits the centre of the detector. Adjust using the red screws.
- 9. Adjust the arm bracket until the laser from the M-unit hits the S-unit in the centre of the target.
- 10. Adjust the laser beam on the M-unit until it hits the centre of the detector.
- 11. Remove the targets.



Rough alignment

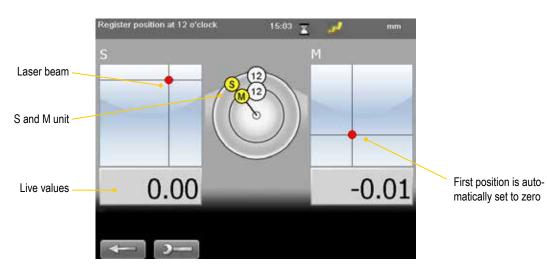
- 1. Adjust the arm bracket until the laser beam from the M-unit hits the centre of the target.
- 2. Adjust the movable machine until both laser beams hit **centre of the targets**.
- 3. Adjust the arm bracket if the adjustment of the machine is not enough.
- 4. Turn the shafts to 9 o'clock. Connectors pointing upwards.
- 5. Adjust the laser beams to the marking for **centre of detector**.
- 6. Remove the targets. The Display unit shows the position of the laser beams.



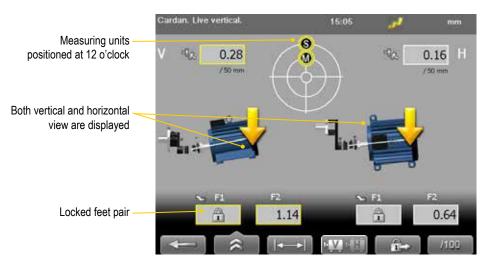
Measure

The shafts are positioned at 9 o'clock.

- 1. Press **OK** to register first position. The first position is automatically set to zero.
- 2. Turn the shafts to 12 o'clock.
- 3. Press **OK** to register position.
- 4. Turn the shafts to 3 o'clock.
- 5. Press **OK** to register position.
- 6. The result for the angular error is displayed.



Result



Function buttons

	Back
_ ≈ _	See "Control panel" on page 15.
	See "Measurement file handling" on page 11.
	Show target . This is a quick way to see where the laser beam hits the target and how the measuring units are positioned.
	Print report on thermal printer (optional equipment). Available when you open a saved measurement.
	Generate report. Available when you open a saved measurement.
	Toggle button. Show vertical or horizontal live values.
* 1	Toggle button to move the lock. By default, the feet pair with the highest value is set to zero and locked.
/100	Toggle button. Switch between to show gap and show angular error per 100 mm. For this to work you need to set the coupling diameter.

Adjustment

Check the machine according to the tolerance and adjust the machine if needed. No offset adjustment is made.

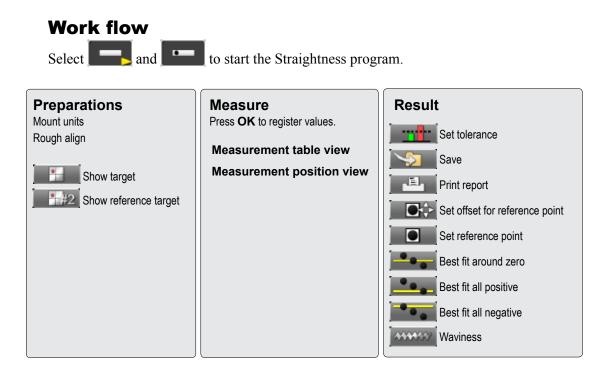
- 1. Adjust the machine vertically by shimming according to the vertical feet values.
- 2. Adjust the machine sideways according to the live horizontal values.
- 3. Tighten the feet.
- 4. Select \bigcirc 1 to remeasure.

STRAIGHTNESS

•

The program Straightness is used for machine foundations, shafts, bearing journals and machine tools for example.

The basic principle for straightness measurement is that all measurement values will show the position of the detector unit relative to the laser beam. First, the laser beam is roughly aligned along the measurement object. The detector is then positioned on the selected measuring points and the values registered.

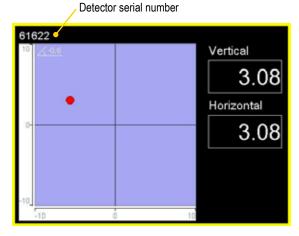


Show target

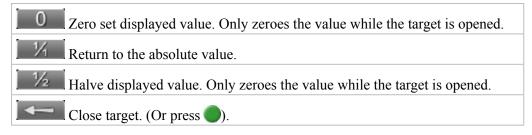
Select **and and to** display a target. This is a quick way to see where the laser beam hits the target and how the detector is positioned. Select **constant** to close the target, or press **o**.

Calculated and raw values

The values displayed here are **raw** values. When you measure, **calculat-ed** values are used. Calculated values are based on the distance from first measurement point and selected reference points.

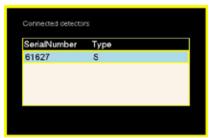


Function buttons

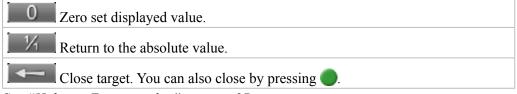


Show reference target

Select **and to** display the reference target. The first time you select the command, a window is displayed. Select which detector you want to use as reference detector and press **.**



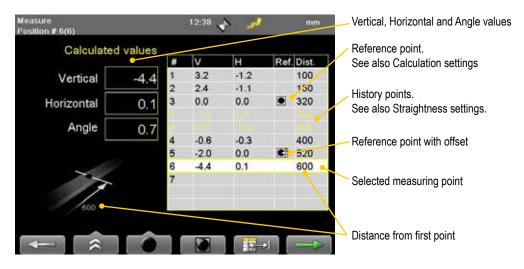
Function buttons



See "Halve or Zero set value" on page 27.

Measure

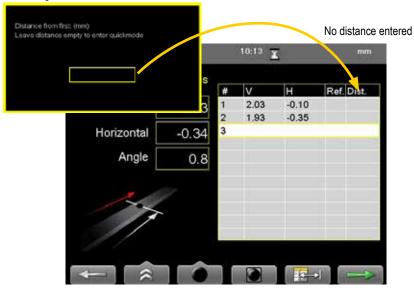
- 1. Press . A window is displayed where you can enter the distance for the measurement point. If you leave the field empty, you can measure using "quickmode".
- 2. Press **()** to register a value. An hourglass is displayed while the value is registered.
- 3. Select _____ to continue to Result view.



Leave program.
See "Control panel" on page 15.
See "Straightness settings" on page 84
Show reference target.
Edit distance . Edit distance for selected point.
Add measuring point.
Delete measuring point.
Go to measuring point . A window is displayed. Enter the point
to which you want to go.
Set offset. Set offset for selected reference point.
Zero set displayed value. Only available before registering the first point. (Or press numerical button zero.)
Return to the absolute value. Only available before registering the
 first point. (Or press numerical button 1.)
Set reference point. See "Result" on page 76.
Open Distance view, see "Enter distances" on page 74.
Continue to Result view. Available when you have registered two points.

Quickmode

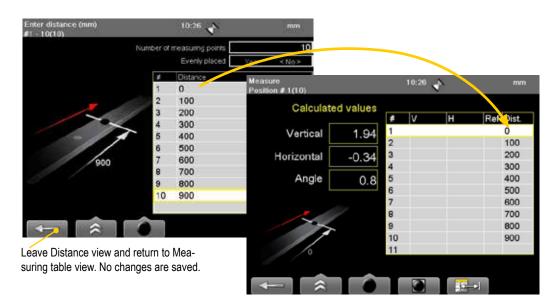
Quickmode means that you measure without entering any distances. Leave field empty to use quickmode.



Enter distances

Select **EVALUATE** to open the Distance view. This is an easy way to fill in many distances. Do this before you have registered a value.

- 1. Enter number of measuring points. Press 🧶
- Select if the points are evenly placed or not. Use navigation buttons left and right. If set to <YES>, you are prompted to fill in the distance between point 1 and 2.
- If set to <No>, fill in each distance in the table.
- 2. Select _____ to save changes and return to Measuring table view.

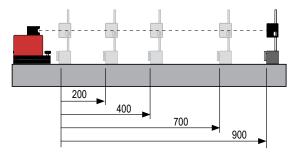


Note!

If you have registered values and open Enter distance view and make changes, your registered values will be deleted.

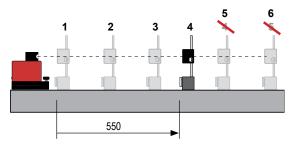
Add and delete points

Distances are always measured from the same point.



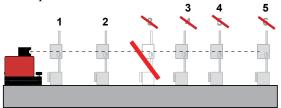
Add measuring point

Adding points between renumbers the existing following points. In this example, we add a new point after point number three.



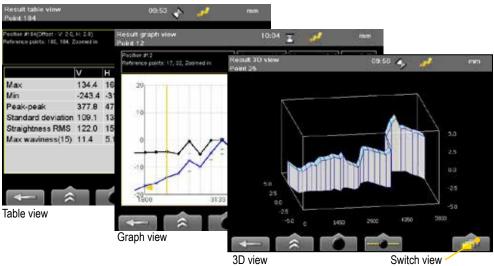
Delete measuring point

Deleting points between renumbers the existing following points. In this example, we delete point number three.



Result

The result can be displayed as graph, table or a 3D view. By default the table view is displayed. The function buttons are almost the same for all three views. Zoom is only available in Graph view. See following pages for more information regarding each view and its functions.



	Back to measure. To remeasure, select a point and then
	Contains a sub-menu:
	See "Control panel" on page 15.
	See "Straightness settings" on page 84.
	Save file . See "Measurement file handling" on page 11.
	Print report . Save file and plug in printer (optional equipment).
	Save report (only when you have opened a saved measurement).
	Set tolerance. It is possible to set different vertical and horizontal toler-
	ance. See "Tolerance" on page 79.
	Zoom . Only available in Graph view.
	Contains a sub-menu:
	Go to measuring point . A window is displayed. Enter the point to which
	you want to go.
	Set offset for reference point . See "Calculation settings" on page 80.
	Contains a sub-menu. See "Calculation settings" on page 80.
	Raw data . Return to original data.
	Set as reference point.
	Remove as reference point . The point itself is not removed.
	Best fit around 0.
	All positive. The best fit with all measurement points above zero.
	All negative. The best fit with all measurement points below zero.
	Show waviness.
1	Views. Switch between table, graph and 3D view.

Result table view

Navigate using the navigation buttons. To remeasure, select a point in the list and select

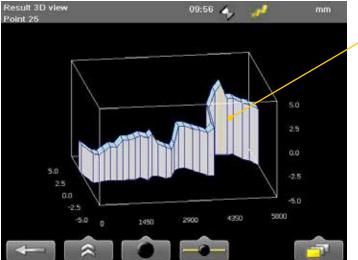
Result table view Point 184			0	9:53	} <i>,</i> ,,∕	mm	
Position #184(Offset - V: 2.0,			#	V	н	Dist.	
Reference points: 180, 184, Z	comed in		179	0.6	-1.2	1780	Reference point
			180	0.0	0.0	1790	
	v	н	181	-0.7	-0.9	1800	Reference point with offset
Max	134.4	165.2	182	-1.3	-0.1	1810	
Min		-313.4	183	-2.1	-1.1	1820	
Peak-peak	377.8	478.7	184	-2.0	-2.0	1830	
Standard deviation		138.1	185	-2.9	-10.2	1840	
		156.7	186	-3.7	-11.1	1850	
Straightness RMS			187	-5.7	-12.8	1860	
Max waviness(15)	11.4	5.1	188	-6.4	-13.8	1870	
			189	-7.2	-14.7	1880	
			190	-7.9	-15.7	1890	
*		ô	- 1	•		_	

MaxThe highest value.MinThe lowest value.Peak-peakDifference between Max and Min valueStandard deviationAverage difference between Max and Min value.Straightness RMSRoot Mean Square (Numerical Flatness)Max wavinessSet waviness is shown in bracket.
See "Waviness" on page 83.

Result 3D view

Navigate using the numeric buttons.

- Buttons 2, 4, 6 and 8 rotates the 3D view.
- Button 5 returns to the initial view.



Selected point



Navigate using the numeric buttons

Result graph view

Navigate using the navigation buttons.



Zoom

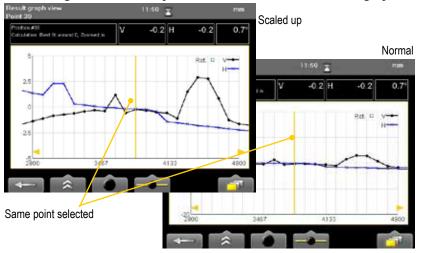
It is possible to zoom in the graph view if you have registered more than 20 points.

Select a measurement point and select and and . The graph is zoomed in around the selected point.



Scale using navigation buttons

Press navigation button "Up" and "Down" to scale the result graph view.



Tolerance

- 1. Select A the tolerance window is displayed.
- 2. Set use tolerance to <YES>. Navigate using the navigation buttons. Press
- 3. Set vertical and horizontal tolerance. Press to confirm each tolerance. The tolerance is shown in the result view.

Use Tolerances	Yes	< No	>
	Min	Max	
Vertical			
Horizontal			

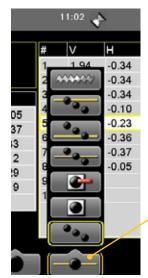


Tolerance in graph and table view

- In the Table view, the values within tolerance are shown in black, values not within tolerance are red.
- In the Graph view, vertical and horizontal tolerances are colour coded.

esult graph view eint 22		13:15	mm					
Posicin#92 Calculation: Best Rt around 0, Zeomet	" V	-0.7 H 2.3	0.7	ð.				
25		Ref. D. V. Tolerances- H. Tolerances- Result table view Point 32				3:15	ŕ	mm
1		Position #32 Calculation: Dest fit arou	and the Reserves		#	v	н	Ref. Dist.
.4		Calculatore Beeting and	no 0, 200mer	s in .	30	-1.1	1.2	2900
	-	<u>/</u>			31	-0.9	2.3	3000
25 The second second second second	and a start of the		v	н	32	-0.7	2.3	3100
		Max	2.9	2.3	33	-0.6	0.3	3200
200 27	4	Min	-2.9	-2.3	34	-0.4	0.2	3300
2100 27	10	Peak-peak	5.7	4.6	35	-0.3	0.1	3400
		Stddev	1.6	1.6	36	-0.4	0.0	3500
← ×	-	RMS	1.8	1.6	37	1.2	-0.1	3600
		Max waviness	1.7	1.0	38	-0.6	-0.2	3700
ertical tolerance					39	-0.2	-0.2	3800
					40	-0.3	-0.2	3900
	al tolerance				41	-0.5	-0.4	4000

Calculation settings



Select to display sub-menu with different calculation settings. Select to revert to original data. All calculations and reference points are removed.

Reference points

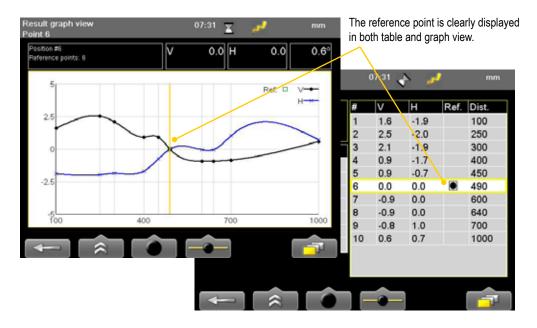
Select and to set selected point as reference point. You can set one or two reference points. To remove a reference point, select it in the table or graph and then select . The point itself is **not** removed. The reference points are clearly displayed in both table and graph.

Note!

You can also set and remove reference points by pressing the green **OK** button.

One reference point

Setting a single reference point will offset all other measurement points based on the set reference point.



Two reference points

Setting two reference points will offset all other measurement points based on a reference line drawn between the two set reference points.



Reference point with offset

By using reference point offset it is possible to move the position of a reference point. This can be used for instance in turbine measurements to compensate for thermal expansion.



Best fit operations

All best three best fit operations will try to find a reference line where the peak to peak value of the measurement points is minimized. This can be used for instance to see if a surface is within given tolerances. The difference between the best fit operations is the offset that is set.

Best fit – around 0

This operation removes all reference points. Centre the values so that the maximum and minimum values are equally large.



Best fit – all positive

Removes all reference points. The best fit with all measurement points above zero.



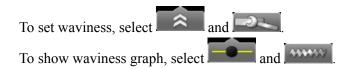
Best fit – all negative

Removes all reference points. The best fit with all measurement points below zero.



Waviness

It may be insufficient to interpret the quality of a measurement by looking only at the measurement peak to peak value. Waviness is often used to detect large deviations. In some applications there might not be a problem with many small deviations, but one large will cause great problems. Bearings in diesel engines is one example.



Example

The two surfaces in the example below have the same peak to peak value. However the first measurement is rougher than the second.

In many applications a smooth measurement is desired. Using waviness it is possible to indicate the smoothness of a measurement. In this example, the rougher measurement will get a waviness graph with higher values.



Two surfaces with same peak-to-peak value

Waviness calculation

The waviness number is calculated by letting a sliding set of reference points traverse the measurement values. The maximum absolute value between the reference points will determine the waviness number at the given position.

Waviness factor 1 checks the deviations between three measurement points. For example between points 1-3, 2-4 and 3-5 etc.

Waviness factor 2 checks the deviations between four measurement points.

Straightness settings

Select **and to** open Straightness settings. For global settings, see "Control panel" on page 15.



Show/hide horizontal values

It is possible to hide the horizontal values. The horizontal values will still be registered, but not visible.

- 1. Select . A window is opened.
- 2. Select Yes or No. Navigate using the navigation buttons.
- 3. Press **OK** to confirm choice.

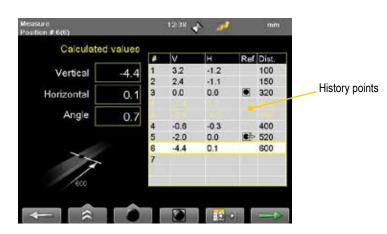
Note!

Only available when you use the program Straightness with a two axis detector.

Show history

If you remeasure a point, the old values are saved as history points. You can select to show or hide these points while measuring. It is only possible to select the latest registered value, not the history points. If you delete a point with history points, all its history is deleted as well. Default is set to hide. Even when set to "hide", the history points are saved and can be viewed later.

- 1. Select . A window is opened.
- 2. Select Yes or No. Navigate using the navigation buttons.
- 3. Press **OK** to confirm choice.

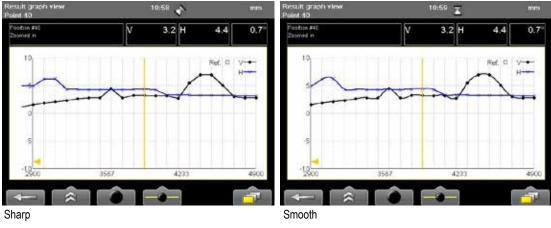


Smooth/sharp graph

1. Select . A window is opened.

- 2. Select Yes or No. Navigate using the navigation buttons.
- 3. Press OK to confirm choice.

When set to Smooth, the graph will find a smooth path between the measurement points.



Waviness settings

- 1. Select . A window is opened.
- 2. Select waviness factor. Navigate using the navigation buttons.
- 3. Press **OK** to confirm choice.

and ANNAN To show waviness in the result view, select



See "Waviness" on page 83.

Same measurement but with waviness



Program to measure flatness of machine bases, machine tables, etc.

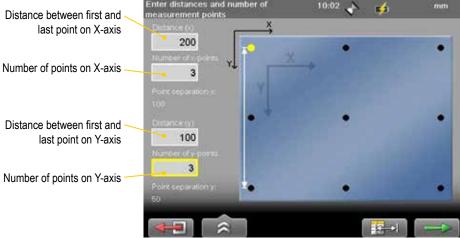
Preparation

- 1. Mount the laser transmitter on the table.
- 2. Mount the detector close to the transmitter on the table (1).
- 3. Select **E** to open the program Flatness and enter distances.
- 4. Select to open the target.
- 5. Select ______ to zero set the value. This is now reference point number one.
- 6. Move the detector to reference point number two (2).
- 7. Adjust the laser beam by using the screw (A) on the tilt table. Level to ± 0.1 mm.
- 8. Move the detector to reference point number three (3).
- 9. Adjust the laser beam by using the screw (B) on the tilt table. Level to ± 0.1 mm.

Repeat procedure until you have all three reference points within ± 0.1 mm.

Enter distances

Up to 500 measurement points can be handled.

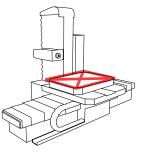


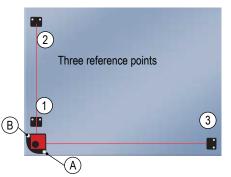
Function buttons

Back. Leave program.
See "Control panel" on page 15.
See "Tolerance" on page 89.
Show target.
Open distance table view. "Distance table view" on page 88.
Continue to Measure view.

Note!

If one of your axis has more than six measurement points, make that the Y-axis. This will give you a better pdf-report.

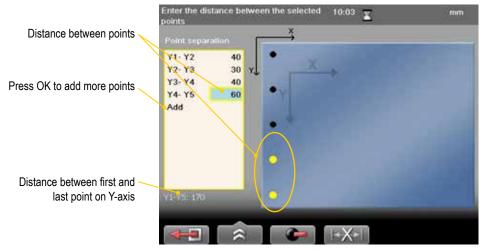






Distance table view

Select to open Distance table view. Use if the distances between points vary in X or Y axis.

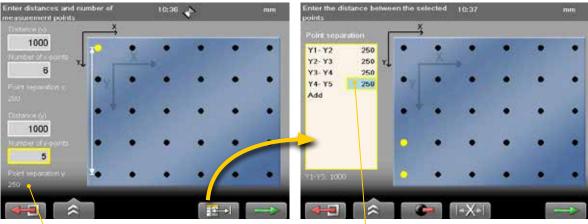


Function buttons

-	Leave Distance table view and return to Distance view. No changes are saved.
*	See "Control panel" on page 15.
	Delete point. It is only possible to delete the last point in the list.
+X+ +Y+	Toggle button. Enter distances for X or Y-axis.
	Continue to Measure view.

Note!

It is also possible to enter distances in the default distance view and switch to Distance table view. This is a fast way if you only need to change one out of many distances

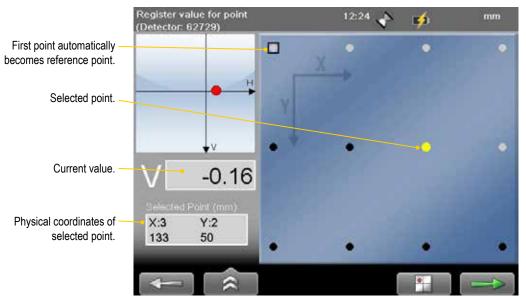


Distance view (default) Point separation is the same for all points

Distance table view Change point separation if needed

Measure

Press **O** to register values. It is possible to measure the points in any order. First measured point is set as reference point. When you have measured all points, the Result view is displayed.



Function buttons

	Back. Return to enter distances.
	See "Control panel" on page 15.
다 문	Measuring direction. Measure left to right or up and down.
	Show target. Useful if you want to rough align for example.
	Continue to Result view. Available when you have measured three positions.

Tolerance

By default, the ISO standard is used. The ISO tolerance is calculated automatically depending on which distances you have entered. Only global tolerance is available.

Select **to** set custom tolerance.

Set custom tolerance	tuose Tolerance	11:42 🕎	mm
	Colorance None Custom tolerance ISO 10791-1 (G15 ISO 10791-2 (G15)	Tolerance value 0.020 Global Tolerance Value 0.030	

Result table

Select **select** to open table view. Values outside the tolerance are displayed with red.

Result table vie 3 reference poi			15:03 📌	· ,1		mm	
Statistics		Value	Point	Value	Ref.	Offset	
Peak-peak		3.103	X:1,Y:1	0.059			Reference point
Min		-1.824	X:2,Y:1	0.000	•		
Max		1.279	X:3,Y:1	0.008			
Standard dev	iation	0.657	X:4,Y:1	0.417			
Flatness RMS	5	0.659	X:1,Y:2	1.263		ľ	Point with offset
Distance data		Value	X:2,Y:2	1.279			
Distance X1-2	(4	100	X:3,Y:2	-0.452		1.000	
Distance Y1-	Y 4	100	X:4,Y:2	-1.824			
Tolerance \	/alue		Point data	0.000	Value		
Туре (Custom tole	rance	Selected Poir	nt	X:3.	(:2	
	0.060		Physical coor	dinate X	67		
			Physical coor	dinate Y	33		More info regarding selected point
			Raw Value		1.44	7	
	*			~	J		

Remeasure selected point.
See "Control panel" on page 15.
Set offset for selected point.
See "Tolerance" on page 89.
Save file, see "Measurement file handling" on page 11.
Toggle button. Set selected point as reference point. Remove as reference.
See "Calculation settings" on page 92.
Raw data. Revert to original data.
Three reference points are automatically set to zero.
Best fit around 0.
All positive. The best fit with all measurement points above zero.
 All negative. The best fit with all measurement points below zero.
See "Result 3D" on page 91.
See "Result grid" on page 91.
See "Result table" on page 90.



Result grid

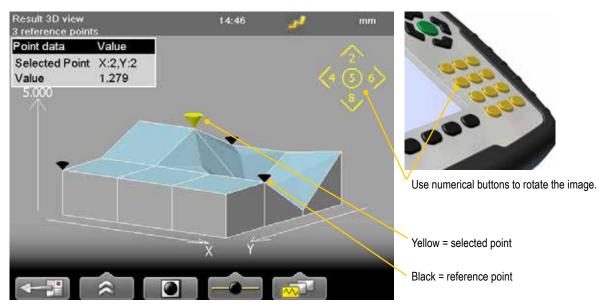
Select **to** open table view.

Result grid view 3 reference points			14:46 🛣	, 1 4		mm	
	X1		X2	Х3		X4	
¥1	0.059	• 0.0	000	0.008		0.417	Red = values not within tolerance
Y2	1.263	1.2	279	-1.452		1.824	Green = values within tolerance
Y3	0.028	0.0	020	0.010	•	0.000	
Y4 🖸	0.000	-0.0	007	-0.017		0.024	
							Reference point
					_		
	\approx		-0-	~~			

Result 3D

Select and to open 3D view. Only available when all points have been measured.

- Use the navigation button to select measurement points.
- Navigate using the numeric buttons.
 - Buttons 2, 4, 6 and 8 rotates the 3D view.
 - Button 5 returns to the initial view.



Calculation settings

Select **select** to display calculation settings. You can try different settings to see which one suits the best and analyze the measurement result directly in the Display unit. You can also save reports with different settings to analyze further later.

Reference points

The measurement values can be recalculated so that any three of them become zero references, with the limitation that a maximum of two of them are in line horizontally, vertically or diagonally in the coordinate system. (If there are three in line, it is just a line, and not a plane!). Reference points are needed when you are going to machine the surface.

Custom reference points

- 1. Select **I** to set currently selected point to zero.
- 2. Select one or three reference points. When you select a second reference point, the values are not recalculated. Set a third reference point to recalculate the values.
- 3. Select **1** if you want to return to raw data.

Set three reference points

- 1. Select **to** set three reference points.
- 2. Select **even** if you want to return to raw data.

Best fit

Best fit around 0

When you perform a best fit calculation, the measurement object is tilted to the lowest peak to peak value. It is fitted as flat as possible between two planes where the average value is zero. Select **for** and **lower** to calculate best fit around 0.

All positive

The measurement object is tilted as in a Best fit calculation, but the reference line is moved to the lowest measurement point. Select **select** and **select** to calculate the best fit with all measurement points above 0.

All negative

The measurement object is tilted as in a Best fit calculation, but the reference line is moved to the highest measurement point. Select **see** and **see** to calculate the best fit with all measurement points below 0.





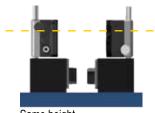
Select

Measure twist on an object by taking two diagonal measurements. If you want to measure a machine foundation made of two beams you can build a temporary reference block at the centre point.

Preparations

and to start the program Twist.

1. Place the S-unit as shown on the screen. Make sure that the Sand M-unit are on the same height. Especially important when you are using a tilt table.



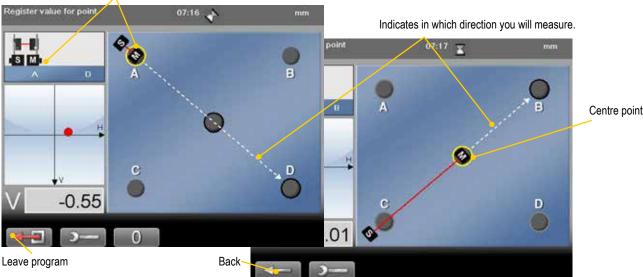
Same height

- 2. Mark where the positions A, B, C and D are on your measurement object. Make sure to place the centre point exactly in the middle.
- 3. Place M-unit on position **D**. Make sure that the laser beam hits the detector target.
- 4. Place the M-unit on the centre point. Make a mark to ensure that you place the detector exactly on the same position each time.
- 5. Place the M-unit on measurement position A.
- 6. Select 0 to zero set the value.
- 7. Move the M-unit to measurement point **D**. Adjust the laser beam to zero (± 0.1) .

Measure

- 1. Place the S-unit as shown on the screen.
- 2. Place the M-unit on measurement position A and press O.
- 3. Follow the instructions on screen and register values on all measurement points.
- When you have registered a value on point **B**, the Result view is automatically displayed.

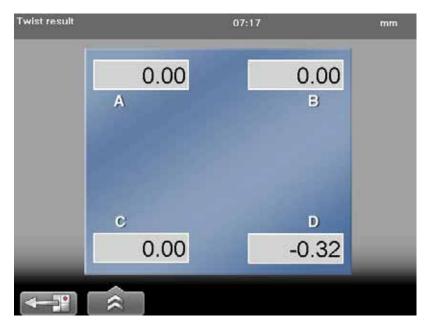
Guide to where to place the measuring unit

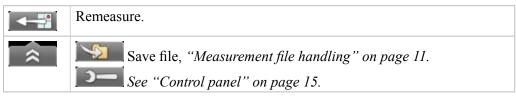


	Back. Leave program.
)	See "Control panel" on page 15.
0	Zero set the displayed value. Only available before registering the first value.
1/1	Return to absolute value. Only available before registering the first value.

Result

Three measurement points are automatically set to zero.





FLANGE FLATNESS

Preparations

- Ensure a good measurement environment. Strong sunlight, warning lights, vibrations and temperature gradients can affect the readings.
- Make sure the surface is clean.
- Use the program Values, Flange flatness or targets for the set up. The tighter the tolerances you require, the more important is an accurate set up and levelling.

Point one

- 1. Place the laser transmitter (D22 or D23) on the flange. Notice the direction, see image.
- 2. Place the detector close to the transmitter.
- 3. Make a mark to mark out the position of the detector.
- 4. Adjust the detector or target until the laser beam hits the centre.
- 5. If you use a measurement program, select **0** to zero set point number one.

Point two

- 6. Move the detector to point number two, see image.
- 7. Adjust the laser beam by turning the screw on the transmitter's tilt table. Level to \pm 0.05 mm or better.

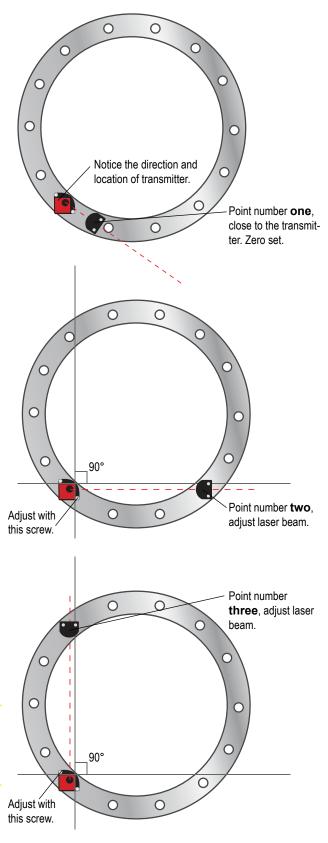
Point three

- 8. Move the detector to point number three, see image.
- 9. Adjust the laser beam by turning the screw on the transmitter's tilt table. Level to \pm 0.05 mm or better.

Repeat procedure until you have all three reference points within ± 0.1 mm.

Note!

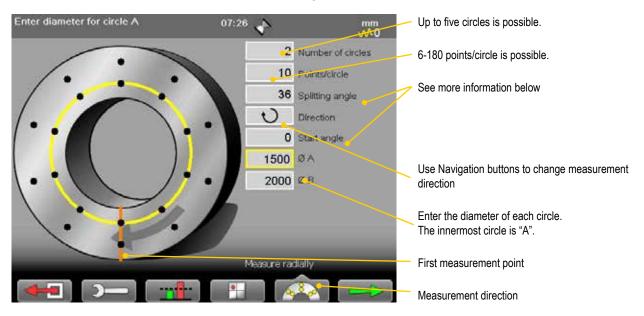
The tilting screws on the laser transmitter have to be operated carefully and according to instructions. See Tilting screws in Technical data.



Enter distances

You can measure 1 to 5 circles of measurement points, for example inner, middle and outer circles, in order to see the taper of the flange. Each circle can have 6 - 180 measurement points. It is possible to measure the points in different orders, inner or outer circle first, or in radially.

- 1. Select *s* and *s* to open the Flange flatness program.
- 2. Enter distances, confirm with .
- 3. Select to continue to measuring view.



Splitting angle

The splitting angle is automatically calculated when you enter the number of measurement points. If you know the splitting angle, it is possible to enter this and get the number of measuring points.

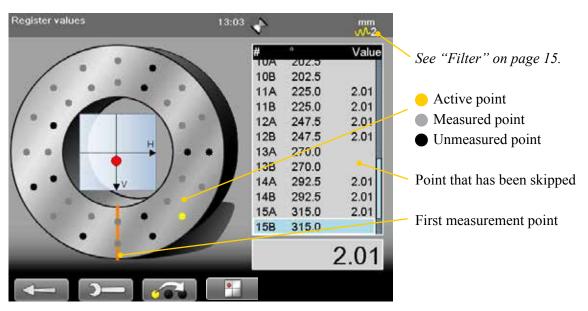
Start angle

As default, the first measurement point is set to 0°. Select a start angle if you want to start somewhere else.

	Back. Leave program.
)—	Open Control panel.
	See "Tolerance" on page 104.
	Show target.
	The measuring order you select is saved and used if you open the file as template or favourite.
	Measure inner circle first.
	Measure outer circle first.
	Measure radially, inner point first.
	Measure radially, outer point first.
	Continue to measure.

Measure

- 1. If you are measuring a flange vertically, secure the laser transmitter with a safety strap. (Part no. 12-0554)
- 2. Press **()** to register measurement values. Registered points are greyed out. Active point is yellow.



+	Back. Press and hold to leave program completely.
)—	Open Control panel.
	Skip point. Only available when it is possible to skip the selected point. Some measurement points are mandatory to ensure an accurate measurement result.
	Show target.
	Continue to result. Available when you have measured all mandatory points.

Result

Flange table view

Select **C** and **C** to display Table view. Use navigation buttons to move in the table. Points marked with * have been skipped when measuring. Skipped points have a calculated value.



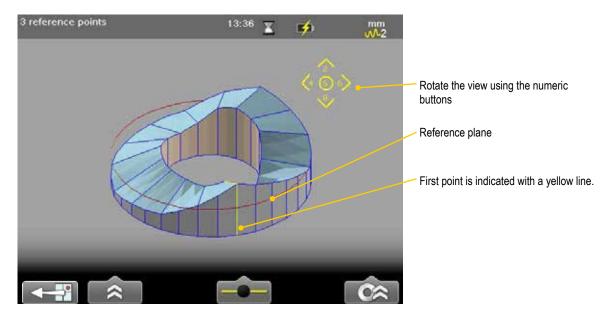
Max	The highest value.
Min	The lowest value.
Peak-peak	Difference between Max and Min value
Standard deviation	Point spread around the mean (average) value.
Flatness RMS	Root Mean Square (Numerical Flatness)

	Remeasure.
*	 Open Control panel. Save. See "Measurement file handling" on page 11. Alter flange diameter. See "Tolerance" on page 104. Print on thermal printer (Optional equipment).
	Add reference point. Or press • to add reference points. Only available in the table view. See "Custom reference points" on page 100.
	See "Best fit" on page 101.
C≈	Switch result view. Different flange and taper views.

Flange 3D view

Select **C** and **C** to display the 3D view. Rotate the view using the numeric buttons.

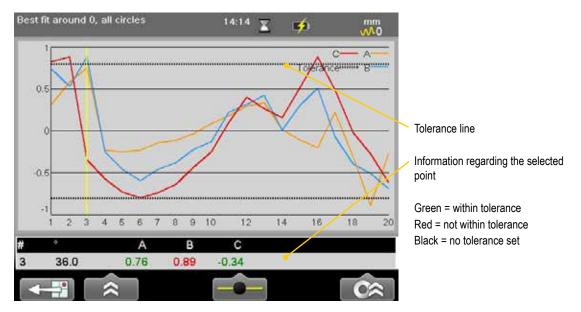
- Buttons 2, 4, 6 and 8 rotate the 3D view.
- Button 5 returns to the initial view.



Same function buttons as in Flange table view.

Flange graph view

Select **c** and **c** to display the Graph view. In this view, you have a good overview of the result. Use the navigation buttons to move in the graph.



Same function buttons as in Flange table view.

Reference points

Reference points are needed when you are going to machine the surface.

You can try different scenarios and analyze the measurement result directly in the Display unit. You can also save reports with different settings to analyze further later. *See also "Best fit" on page 101.*

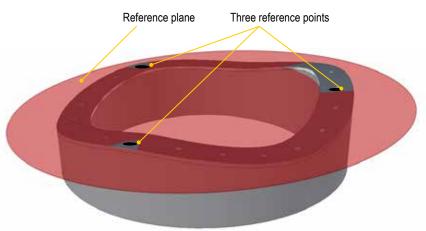


Custom reference points

- 1. Select a measurement point in the Table view.
- 2. Select **ID** to set currently selected point to zero. Or press .
- 3. Select one or three reference points. When you select a second reference point, the values are not recalculated. Set a third reference point to recalculate the values.
- 4. Select **e** if you want to return to raw data.

Three reference points

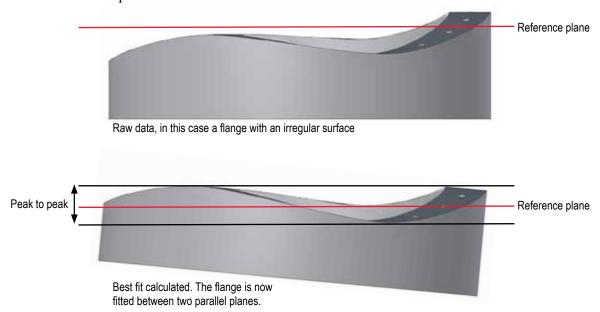
- 1. Select **set** and **set** to set three reference points. Three points with the lowest peak to peak value are set to zero.
- 2. Select **even** if you want to return to raw data.



The reference plane is resting on three reference points.

Best fit

When you perform a best fit calculation, the flange is tilted to the lowest peak to peak value. It is fitted as flat as possible between two planes. See example below:



Best fit around zero

Select **select** and **select** to calculate best fit around 0. Select one or all circles.

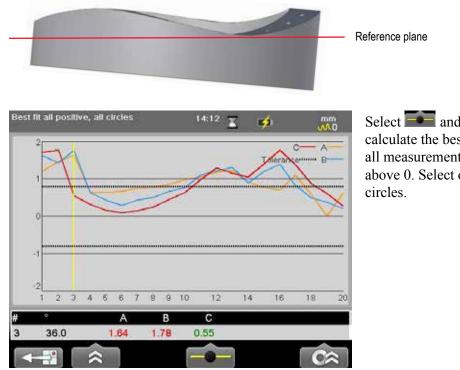


Note!

You can save reports with different settings for best fit to analyze further later.

Best fit all positive

The flange is tilted as in a Best fit calculation, but the reference line is moved to the lowest measurement point.



Select and to calculate the best fit with all measurement points above 0. Select one or all

Best fit all negative

st fit all negative, all circles

6 6

-0.13

A

3

36.0

The flange is tilted as in a Best fit calculation, but the reference line is moved to the highest measurement point.

4



9 10

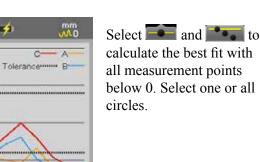
В

0.00

8

12

-1.23



Reference plane

16 14 18

Taper result

If you have measured two or more circles, you can calculate taper. Taper values can be displayed as graph or table. The taper values are recalculated when you select a different Best fit.

From the Result view, select and and and an arrow of outer circle minus inner circle is displayed. To calculate a different taper value, select .

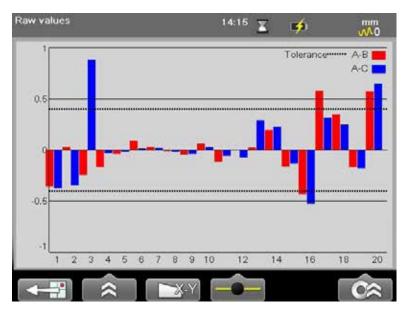
Taper table

Select **and to display Taper table.** Here you get a good overview of the inclination of the flange, between the measured circles. Use navigation buttons to move in the table.

Best fit around 0, all circles			14:11	1	mm vA0	
#	°	A-B	A-C			
1	0.0	-0.42	-0.51			
1 2	18.0	0.05	-0.30			
3	36.0	-0.13	1.10			
4	54.0	0.02	*0.34			
5	72.0	*0.21	*0.48			
6	90.0	*0.37	*0.57			
7	108.0	0.32	0.59			
8	126.0	*0.26	*0.52			
9	144.0	0.18	0.40			
10	162.0	0.21	0.33			
11	180.0	^-0.04	°0.08			
12	198.0	-0.02	-0.11			
13	216.0	-0.09	0.07			
14	234.0	0.01	-0.15			

Taper graph

Select **and** and **to** display Taper graph. Use the navigation buttons to move around in the graph.



Tolerance

It is possible to set tolerance on Taper and/or Best fit.

- 1. Select and .
- 2. Enter tolerance values for Best fit and/or Taper.
- 3. Turn the tolerance on/off by

	Choose best	fit tolerance	-	15	:59 🕎	\$	
Activate/deactivate tolerance		Value Active	Min	-0.8	Max	0.8	
		Taper Active	Min	-0.4	Max	0.4	
	-	[— C]	•~*				

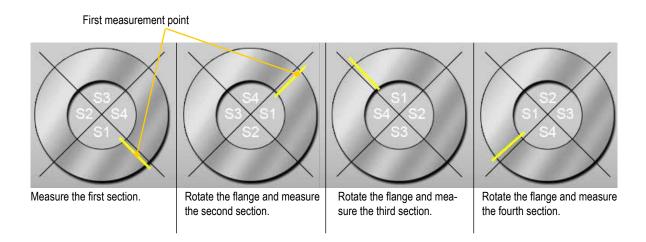
Tolerance is displayed both in graph and table view.



FLANGE FLATNESS SECTION



The program Flange Flatness Section is primarily used for large flanges. The flange is divided into four sections and rotated for easy measuring. Thanks to the fact that you only measure the lower part of the flange, there is no need to climb to fasten detectors or laser transmitters.



You can measure 1 to 5 circles of measurement points, for example inner, middle and outer circles, in order to see the taper of the flange. Each circle can have 16 - 180 measurement points. The program guides you graphically step-by-step through the entire measurement.

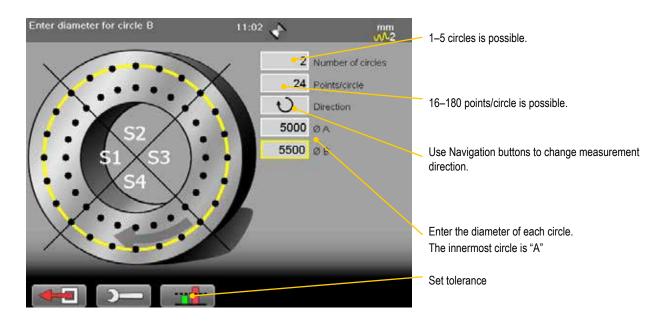
Note!

International patent pending (PCT/EP2014/052631)

Preparations

Enter distances

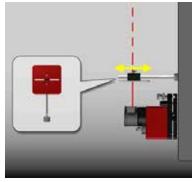
- 1. Select **I** and **I** to open the Flange flatness section program.
- 2. Enter distances, confirm with 🧶.



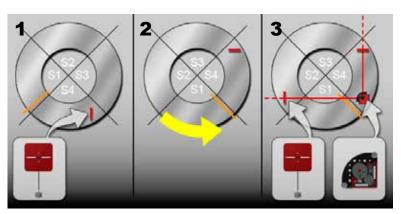
Visual targets

Adjust all three visual targets; place the target close to the laser transmitter and make sure that the laser beam goes through the slit.

- 1. Mount a target on the flange. Where you place it depends on which measurement direction you have chosen. Follow the instructions on screen.
- 2. Rotate flange. Note the direction on the screen.
- 3. Mount the laser transmitter and a laser target as shown on screen. Secure the laser transmitter with a safety wire. (Part no. 12-0535). Adjust laser transmitter if needed.



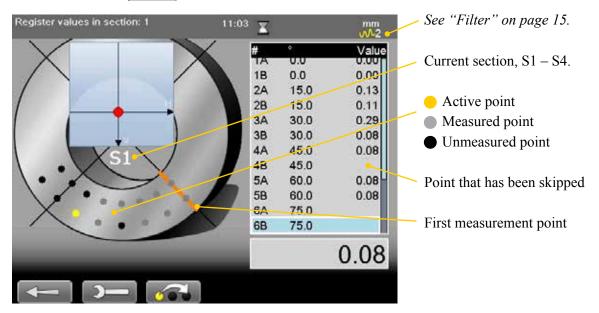
Adjust all three targets



Follow instructions on the screen

Measure

- 1. The first measurement point is marked with a line. Active point is yellow.
- 2. Press on to register measurement values. Registered points are greyed out.
- 3. Select **continue** to next section.

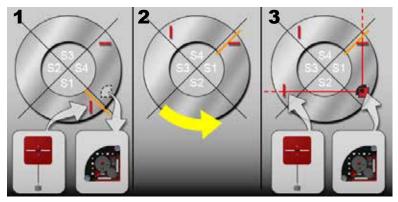


Function buttons

	Back. Press and hold to leave program completely.
)—	Open Control panel.
	Skip point. Only available when it is possible to skip the selected point. Some measurement points are mandatory to ensure an accurate measurement result.
	Available when you have measured all mandatory points. When you leave the current section, it is not possible to go back to remeasure.

Rotate flange

- 1. Remove laser transmitter and place a target as shown on the screen.
- 2. Rotate flange. Note the direction on the screen, it is contrary to the selected measurement direction.
- 3. Mount the laser transmitter and a laser target as shown on screen. Secure the laser transmitter with a safety wire. Adjust laser transmitter if needed.



Result

The result can be shown as table, graph or 3D. If you have measured two or more circles, you can see Taper result. See *Flange Flatness "Result" on page 98*.

Reference points

It is possible to set custom reference points or to select three reference points automatically.

See "Reference points" on page 100.

Best fit

When you perform a best fit calculation, the flange is tilted to the lowest peak to peak value. It is fitted as flat as possible between two planes. See *"Best fit" on page 101.*

Taper

If you have measured two or more circles, you can calculate taper. See *"Taper result" on page 103.*

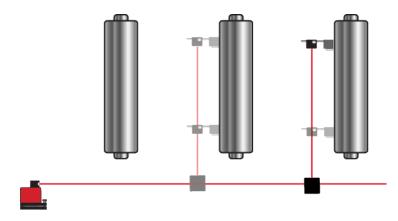
Tolerance

It is possible to set tolerance on Taper and/or Best fit. See *"Tolerance" on page 104.*

PARALLELISM A



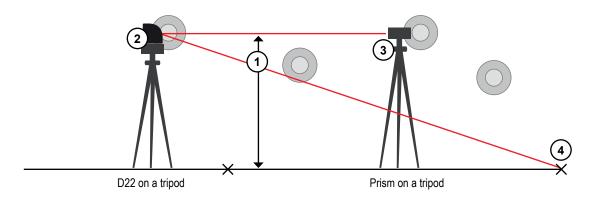
Examples of parallelism measurement include mutual parallelism between rolls and other surfaces in papermaking machines, printing presses, rolling mills, etc. Other examples include overhead tracks, rails, press machine tables.



Laser setup

To establish a good reference line, it is important to set up the laser correctly. The reference line is often a line alongside the machine, but can also be a fixed object in the machine.

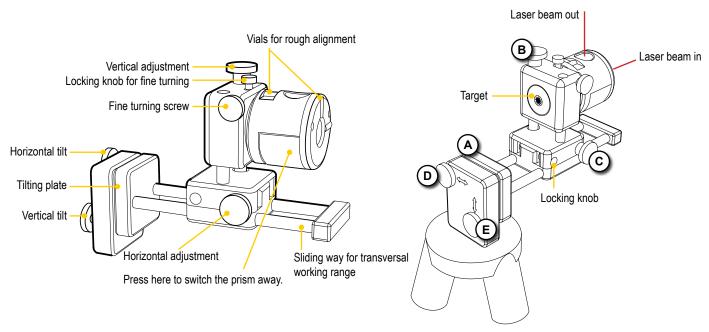
- 1. Mount the laser on the same height as the prism.
- 2. Level the laser according to the spirit level.
- 3. Adjust the prism so that the laser beam hits the centre of the target. See "*Prism set up*" on page 110.
- 4. Direct the laser beam along the machine, and perpendicular to the measurement object. Use targets, or mount detectors to set up the reference line.



Prism set up

- 1. Mount the angular prism on the sliding bracket and place it on a tripod.
- 2. Switch the prism on the D46 to let the beam hit the target.
- 3. Slide the prism toward (A) and adjust the offset with (B) and (C) until the target is concentric to the laser beam.
- 4. Slide the prism away from (A) and adjust the angle with (D) and (E) until the target is concentric to the laser beam.
- 5. Repeat 3 and 4 until the beam is centered on the target in both outer and inner position.
- 6. Switch the prism in, tighten the locking knob and measure.

Now the angular prism can be moved to a new position on the sliding way to aim the laser beam to the detector.



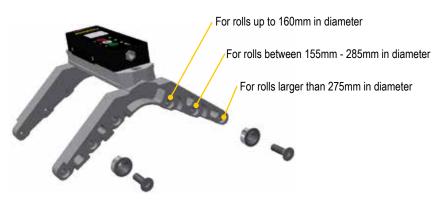
Angular prism mounted on tripod

Precision level

The precision level is used to measure the vertical value. It is possible to skip the Precision level for all or single rolls. See also "*Precision level E290*" on page 221.

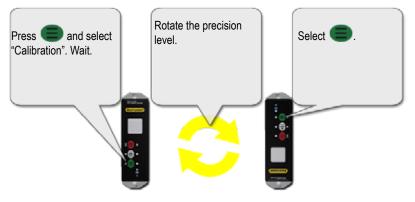
Bracket for different roll sizes

Use the bracket to ensure that the Precision level lands firmly on the roll. Mount the wheels in the appropriate position and then calibrate the Precision level. If you change position of the wheels, you need to calibrate the Precision level again.



Calibrate the precision level

- 1. Place the Precision level on the reference roll. Make a mark on the roll to ensure that you place it in the same position.
- 2. Press **(**) and select "Calibration".
- 3. Wait approx 15 seconds, until the value has stabilized. Press 🔵.
- 4. Rotate the Precision level 180°.
- 5. Wait approx 15 seconds, until the value has stabilized. Press (). The Precision level has been calibrated. The calibration is saved even when the Precision level is switched off.



Note!

When you use the Precision level, it has to be switched on during the whole measurement.

Set up Bluetooth®

Make sure that the Precision level is connected to the Display unit via Bluetooth®.

- 1. Select and to open the Control panel.
- 2. Select **I** to open the Bluetooth[®] view.
- 3. Select to search for Bluetooth[®] units.

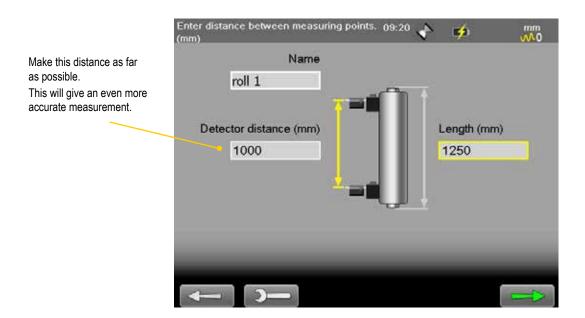
See also "Bluetooth® set up" on page 21.

Measure

Enter distances

- 1. Enter a name or keep the default name. Press 🧶
- 2. Enter the distance between the detectors. Measure between the rods.
- 3. Press **()** to continue to Measure view, or use navigation button to enter the distance between the adjustment points.

The distance between adjustment points is not mandatory. If you leave the space empty, it will be filled in with the same length as the detector distance.



Measure vertical value

The vertical value is measured with the Precision level. For a correct measurement result, it is very important that you place the Precision level in the same direction on all rolls.

- 1. Adjust the Precision level until the yellow arrow is within the green area.
- 2. Wait until the value has stabilized (approx. 15 sec.)
- 3. Press on to register measurement value.

The value is shown as mm/m or inch/foot. When it is not possible to register a value, the bubble turns red and the value is shown in degrees. To change unit, see *"Unit and resolution" on page 16.*



Place the Precision level in the same direction on all rolls!



Function buttons

	Back to Distance view.
)—	See "Control panel" on page 15.
	Skip measuring with the Precision level for all rolls . It is possible to turn it back on again from the result view.
	Continue. Skip measuring with the Precision level for this roll .

Skip Precision level

It is possible to skip measuring with the Precision roll. When you do, you will not have a vertical value in the result view.

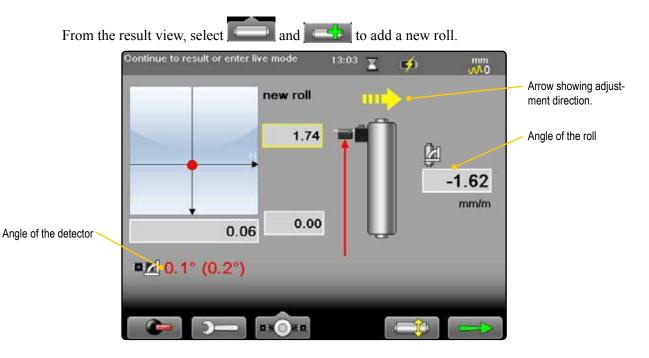
Note!

If you use cables to your detectors, remove the cable from the Display unit before measuring using the Precision level.

Measure horizontal value

The horizontal value is measured with the detector.

- 1. Place the detector on the roll. The Display unit will recognize how the detector is placed. If you want to change it, use
- 2. Use the navigation buttons to change the active measurement position.
- 3. Angle the laser beam along with the roll. See "Prism set up" on page 110.
- 4. Adjust the laser beam via the prism until you hit the centre of the target.
- 5. Press b to register the first position.
- 6. Move the detector to the second position.
- 7. Press 🔵 to register the second position. The angle of the roll is displayed.
- 8. Press b to go to Result view. Or select to adjust the roll.

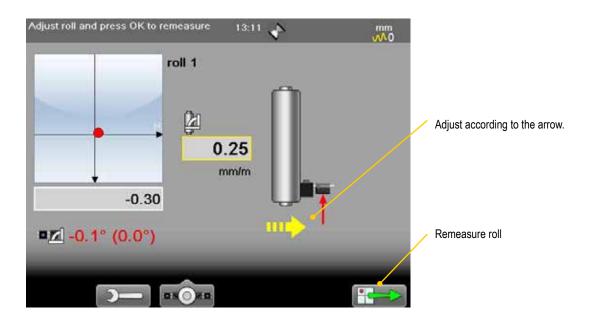


Function buttons

	Remove latest registered measurement point.
)—	See "Control panel" on page 15.
BNONB	Automatic recognition, the Display unit recognizes how the detector is placed. The detector is placed on the right side. The detector is placed on the left side.
	Go to live adjustment view. See "Adjust roll live" on page 115.
	Forward to Result view.
	Forward from Adjust view. When you have adjusted a roll, you need to remeasure the roll.

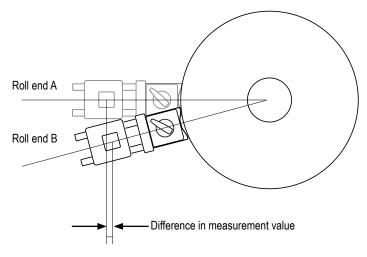
Adjust roll live

- 1. From the Measure view, select **1** to adjust the roll live.
- 2. Adjust the roll according to the arrow.
- 3. Press or to continue. The Measuring view is displayed and you are prompted to remeasure the adjusted roll before you can continue.



Detector angle

The position of the detector affects the measurement value when measuring parallelism. Therefore it is important to place the detector at the same angle at measurement position 1 and 2. At a 500 mm radius an angular deviation of 1° will cause a 0.1 mm difference in the measurement value.



Result

Table view

By default, the table view is displayed.

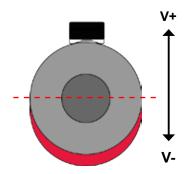


Vertical values

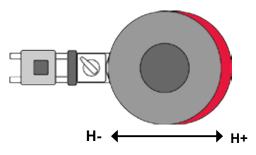
The vertical value is measured with the Precision level.

Horizontal values

The horizontal value is measured with the Detector. When reading the horizontal value, face the laser transmitter from the roll. Then the value correspond to the measurement program.



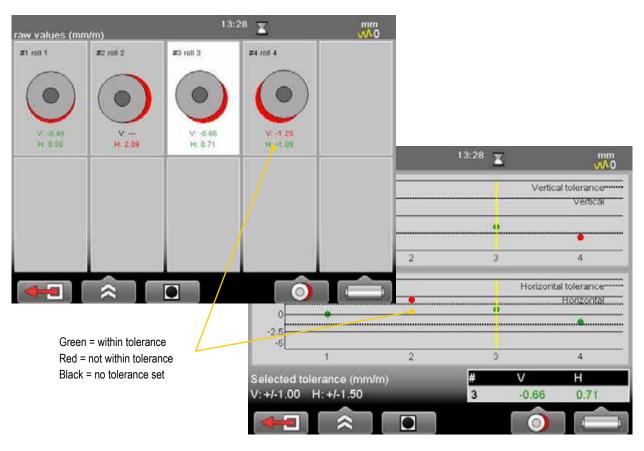
In this example, the roll has a negative vertical value.



In this example, the roll has a positive horizontal value.

Side and Graph view

The Side view and Graph view are great when you want to get an overview of all rolls.



Function buttons

	Leave program.
	See "Control panel" on page 15.
	See "Measurement file handling" on page 11.
	See "Tolerance" on page 118.
	Alter distance and/or name on roll.
	Turn the Precision level on/off.
	Toggle button. Set selected roll as reference. Or press O.
0	Show Result table view.
	Show Result side view.
	Show Result graph view.
Ì	Add a new roll and measure it. Adjust and/or remeasure selected roll.

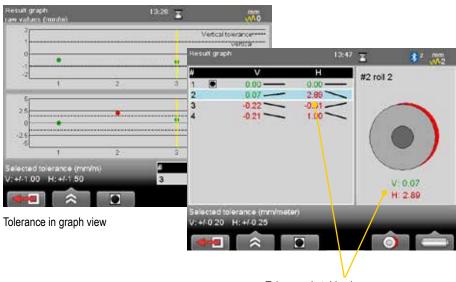
Tolerance

Select and to set tolerance.

- The maximum value has to be greater than the minimum value.
- When you use Metric (mm) two decimals is possible
- When you use Imperial (inch/foot), four decimals is possible

Vertical (mm/m)	
On/Off ✔ X	Min -0.25	Max 0.20
Horizonta	al (mm/m)	
On/Off	Min	Max
 ✓ X 	-0.25	0.25

It is possible to set tolerance and then deactivate it. A deactivated tolerance is not used in the measurement.



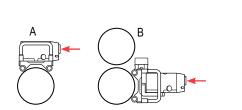
Tolerance in table view

PARALLELISM B



Parallelism B is used for fast replacement and alignment of rolls in, for example, printing presses, paper machines and converting machines. Easy-Laser® E975 offers precision of up to ± 0.02 mm/m (0.001 degree).

First you measure the vertical angle, then the horizontal. Maximum distance between transmitter and detector is 20 metres. The rolls can be mounted at different heights.



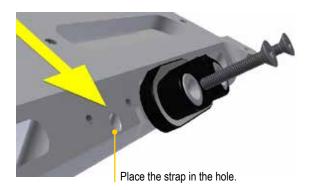
Alternative mounting of units: A: Top attachment B: Front attachment. If space on top is limited.



Mount the security strap

- 1. Unscrew the security strap lock.
- 2. Place the end of the security strap in the hole.

3. Screw the lock back in place. Make sure that the strap is securely in place. Before each measurement, make sure that the security strap is undamaged.

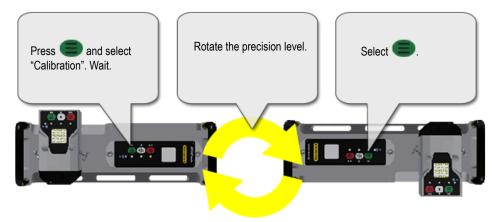


Preparations

The precision level is used to measure the vertical value. It is possible to skip the Precision level for all or single rolls. When you use it, the Precision level has to be switched on during the whole measurement.

Calibrate the precision level

- 1. Place the bracket with the Precision level on the reference roll. Make a mark on the roll to ensure that you place it in the same position.
- 2. Press (and select "Calibration".
- 3. Wait until the value has stabilized. Press 🥌
- 4. Rotate the Precision level 180°.
- 5. Wait until the value has stabilized. Press (). The Precision level has been calibrated. The calibration is saved even when the Precision level is switched off.



See also "Precision level E290" on page 148.

Note!

When you use the Precision level, it has to be switched on during the whole measurement.

Set up Bluetooth®

Make sure that the Precision level is connected to the Display unit via Bluetooth[®].

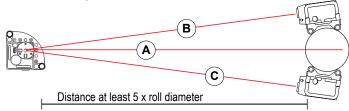
- 1. Select and to open the Control panel.
- 2. Select **I** to open the Bluetooth[®] view.
- 3. Select **Select** to search for Bluetooth[®] units.

See also "Bluetooth® set up" on page 21.

Unit serial	Con	nect
75864	1	×
95456	1	X
72409	A	×
59048	4	×

Calibrate E2 detector

The detector is mounted and calibrated on the factory. If you loosen the detector, you need to calibrate it on site. If you have zero set the E2 detector, you must restart it before calibrating it.

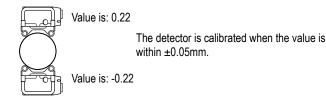


- 1. Place the laser transmitter parallel to the roll (A) and level it according to the spirit level. The distance between the roll and the laser transmitter should be at least five times the diameter of the roll.
- 2. Place the bracket with detector on the top of a roll (**B**). The green diode on the detector is lit up when the laser beam hits the detector.
- 3. Level the laser to H value ± 1 mm/m.
- 4. Press 🔵 and select "Calibration".
- 5. Select Horizontal and press () to register a value.
- 6. Place the bracket with detector under the roll (C).
- 7. Press () to register a value.
- 8. Press () to accept the offset value.

The detector has been calibrated. The calibration is saved even when the detector is switched off.

Check calibration

You can easily check the calibration. Place the detector on the top of a roll. Note the value. Place the detector under the roll and read the value. If the value is for example 0.22 on the top, a calibrated detector will then display -0.22 (\pm 0.05mm) on the bottom.



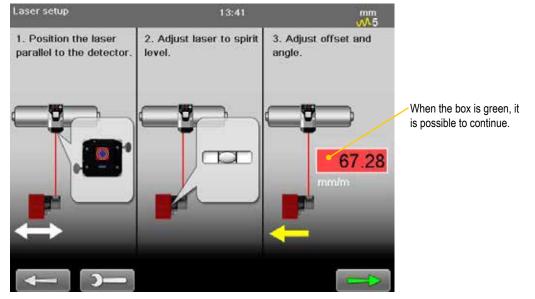
Reset

Press e and select "Reset" to return to factory settings.

Laser setup

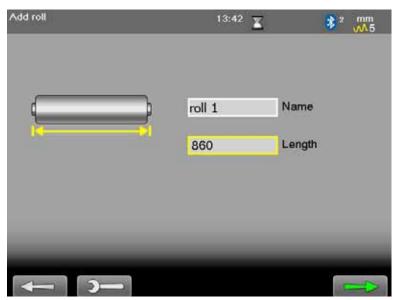
To establish a good reference line, it is important to set up the laser correctly. The green diode on the detector is lit up when the laser beam hits the detector.

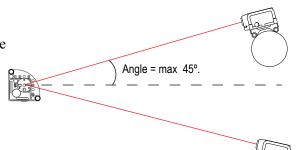
- The distance between the roll and the laser transmitter should be at least five times the diameter of the roll.
- The angle between the rolls should no more than ± 45 degrees, see image.
- 1. Adjust the offset by moving the laser transmitter.
- 2. Adjust the laser transmitter to spirit level.
- 3. Adjust the offset and angle. When the value box is green, it is OK to continue.
- 4. Select **b** to continue.



Enter distances

- 1. Enter a name or keep the default name.
- 2. Enter the distance between the adjustment points. It is not mandatory.
- 3. Press **()** to continue.





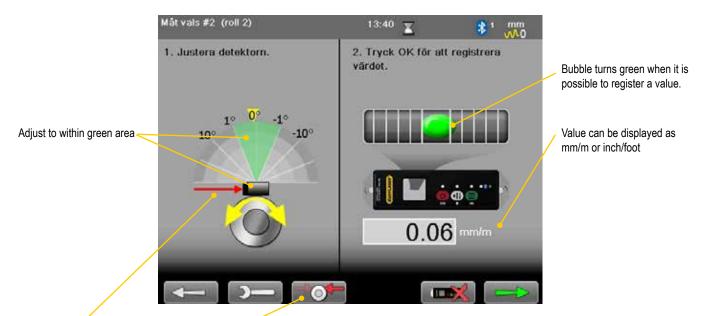
Measure

Measure vertical value

The vertical value is measured with the precision level.

- 1. Check your measurement direction. Switch direction if needed.
- 2. Adjust the fixture until the yellow arrow is within the green area. See image.
- 3. Wait until the value has stabilized (approx. 15 sec.)
- 4. Press **o** to register measurement value.

The value is shown as mm/m or inch/foot. When it is not possible to register a value, the bubble turns red and the value is shown in degrees. To change unit, see "Unit and resolution" on page 16.



Check your measurement direction Switcl

Switch measurement direction

Function buttons

	Back to Distance view.
) –(See "Control panel" on page 15.
- 0 +	See "Switch measurement direction" on page 124.
	Skip measuring with the Precision level for all rolls . It is possible to turn it back on again from the result view. Use with care, the value from the level is is used to calculate the horizontal value.
	Select to continue without measuring this roll using the Precision level.

Measure horizontal value

The horizontal value is measured with the E2 detector.

- 1. Adjust the bracket/roll until the laser beam hits the detector. You need to be within the green area to measure.
- 2. Press on to register measurement value. The result view is displayed.



Adjust to within green area

Switch measurement direction

It is possible to switch measurement direction. To ensure an accurate measurement when you switch direction, it is important that the precision level has been indexed. See *"Calibrate the precision level" on page 120.*

Select **mot** to switch direction.



Result

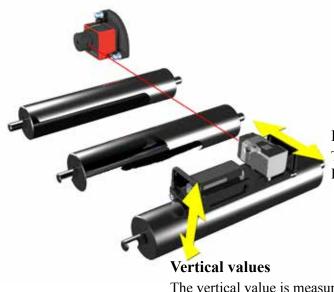
Table view

By default, the table view is displayed.



Face the laser

When reading the values, face the laser transmitter from the roll. Then the value corresponds to the measurement program.

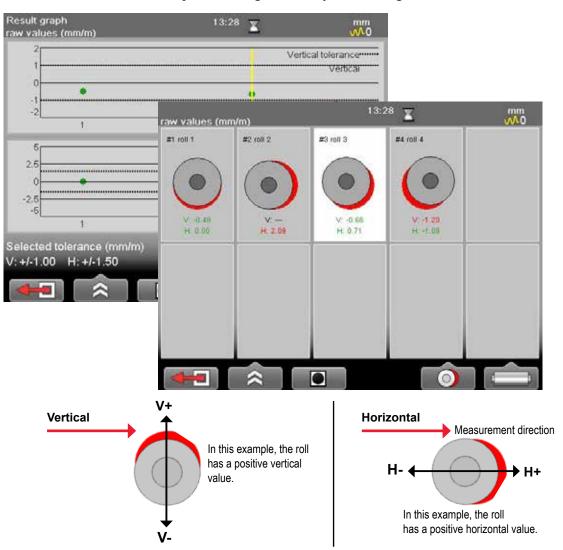


Horizontal values The horizontal value is measured with the Detector E2.

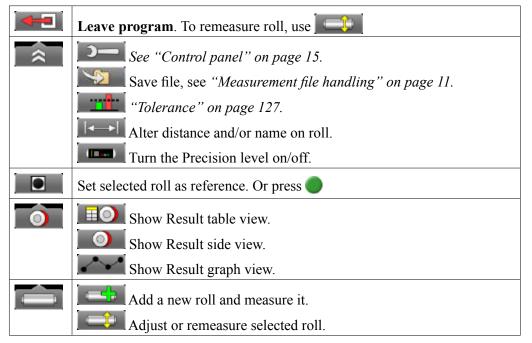
Vertical values The vertical value is measured with the Precision level.

Side and Graph view

The Side view and Graph view are great when you want to get an overview of all rolls.



Function buttons



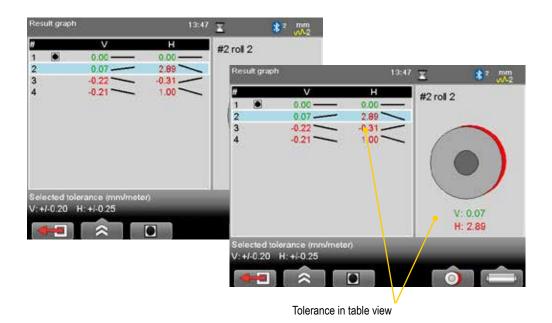
Tolerance

Select and to set tolerance.

- The maximum value has to be greater than the minimum value.
- When you use Metric (mm) two decimals are possible
- When you use Imperial (inch/foot), four decimals are possible

On/Off Min Max -0.25 0.20 Horizontal (mm/m) On/Off Min Max	Vertical (n	nm/m)				
-0.25 0.20 Horizontal (mm/m)	On/Off	Min		Max		
	4X		-0.25		0.20	
UN/UT MIN Max		S 8)			
-0.25 0.25	A CONTRACTOR OF	Min	-0.25	Max	0.25	

It is possible to set tolerance and then deactive it. A deactivated tolerance is not used in the measurement.







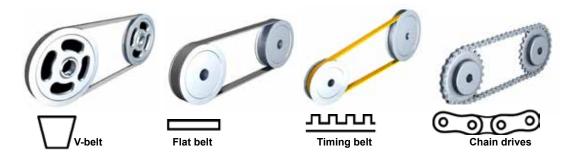
Easy-Laser® BTA system consists of a laser transmitter and a detector. Magnetic mountings on laser and detector make it easy to mount the equipment. Non-magnetic sheave/pulleys can be aligned as the units are very light and can be mounted using double-sided tape.

Note!

BTA is not included in the Shaft or Geo systems but bought as an option. For technical information, see "BTA E180 (Optional)" on page 146.



All types of sheave/pulleys can be aligned, regardless of belt type. You can compensate for sheaves of varying widths.



The misalignment can be offset or angular. It can also be a combination of both.

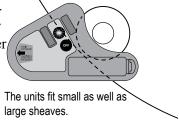


Preparations

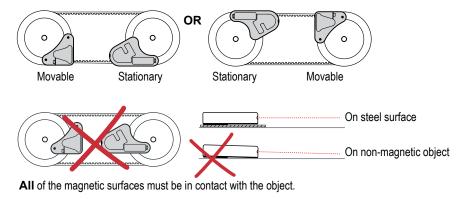
- Check the sheaves for radial runout. Bent shafts will make it impossible to perform an accurate alignment.
- Check the sheaves for axial runout. If possible, adjust with the mounting screws of the bushings.
- Make sure that the sheaves are clean from grease and oil.

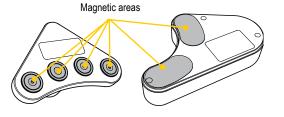
Mount the units

The units are mounted on a flat machined surface with magnets. The magnets are very strong, try to soften the touch by putting just one magnet to sheave first, then turning the other ones in. Non-magnetic sheave/pulleys can be aligned as the units are very light and can be mounted using double-sided tape.

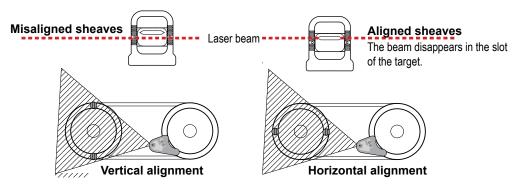


- 1. Mount the laser transmitter on the stationary machine.
- 2. Mount the detector on the movable machine.
- 3. Make sure all magnetic surfaces are in contact with the sheave.





Align with targets

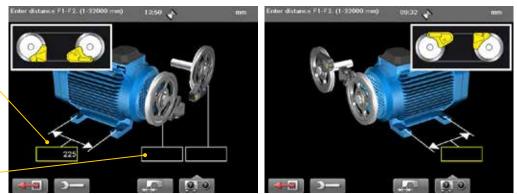


Measure using Display unit

The E180 BTA can be used as a separate tool, see "*Measure without Display unit*" on page 134.

Enter distances

- 1. Connect to the Display unit via cable or use Battery pack with Bluetooth[®].
- 2. Press the ON button on the laser transmitter.
- 3. Select **2** to open the BTA program.
- 4. Select **I** if you want to enter sheave face width. Press **OK**.
- 5. Enter distance between feet pairs. Press OK.



Movable machine is to the right.

Movable machine is to the left.

Function buttons

Distance between feet pairs **Mandatory**

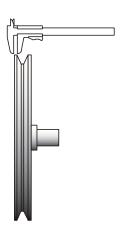
Sheave face width Optional

runction	
	Leave program.
)—	See "Control panel" on page 15.
+#+	Sheave face width . Select to activate fields if the sheaves have different face widths.
00	Contains a sub menu.
	The Display unit automatically recognize where the units are placed.
	However, you can do this manually as well.
	Set M-unit to the left.
	Set M-unit to the right.
	Return to Automatic configuration.

Sheave face width

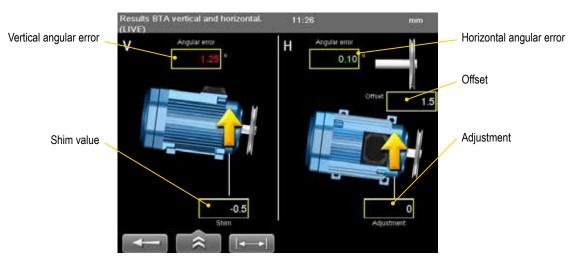
The distance from the belt to the axial face of the sheave can be different on the two sheaves. To calculate a possible offset the system requires both sheave face widths.

- 1. Measure the distance from the belt to the axial face of the sheave.
- 2. Select **I** to activate fields and enter distances.



Measure

Make sure that the laser line hits the detector aperture. The Display unit shows the offset and angular misalignment.



Function buttons

	Back. Return to enter distances.
*	See "Control panel" on page 15. Save, see "Measurement file handling" on page 11. Set tolerance. See also Tolerance on next page. Print on thermal printer (Optional equipment). Available when you have saved the measurement.
[←→]	Edit distance.

Values – colours

White	No tolerance set.
Green	Value within tolerance.
Red	Value outside tolerance.
++++	Loss of signal, laser beam interrupted for example.

Note!

The laser transmitter flashes when the battery is low. Change the batteries before you continue to measure.

Recommended

Tolerance

Recommended maximum tolerances from manufacturers of belt transmissions depends on type of belt, usually between 0.25–0.5°.

- . The tolerance view is displayed. 1. Select Set tolerance 14:52 <u>а</u>, mm mm/m <° mils/inch Angular error No tolerance 0.1 1.75 0.10° 0.2 3.49 0.20° 0.3 5.24 0.30° 0.4 6.98 0.40° 0.50 0.5 8.73 0.6 10.47 0.7 12.22 0.8 13.96 0.9 15.71 1.0 17.45 2.1
- 2. Select **Putt** to set user defined tolerance.

Adjust

Start by adjusting the sheave, and then the machine.

- Correct offset by moving the movable machine with axial jackscrews, or by repositioning one of the sheaves on its shaft.
- Correct vertical angular error by shimming the movable machine.
- Correct horizontal angular error by adjusting the movable machine with lateral jackscrews.

When you adjust the machine one way, it often affects the machine's other alignment conditions. Which means this process may have to be repeated several times.

Note!

If not using the system for a long period of time, remove the batteries.

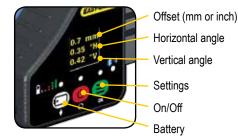
BTA

Measure without Display unit

The E180 BTA can be used as a separate tool.

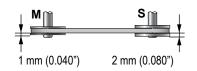
Measure

- 1. Press (1) to start the detector and ON to start the laser transmitter.
- 2. Read the values. Offset, horizontal angle and vertical angle are displayed.
- 3. Adjust machine, see previous page.



Different sheave width

If the sheaves have different face widths, just add or subtract the difference from the zero value to get the value for perfect alignment.

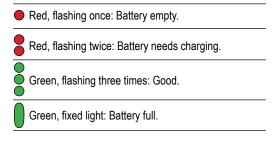


Settings

- Press 🕤 to switch position on the M and S-unit.
- Toggle between mm and inch with **S**.

Battery

Press \bigcirc to see the battery status of the detector. While the battery is charging, there is a green flashing light. The laser transmitter flashes when the battery is low. Change the batteries before you continue to measure.



Note!

If not using the system for a long period of time, remove the battery from the laser transmitter.

VIBROMETER



Easy-Laser® Vibrometer is used in preventive as well as active maintenance work on rotating machinery. It measures the vibration level and bearing condition of machinery.

When measuring vibration level, Easy-Laser® Vibrometer is measuring the effective velocity (mm/s or inch/s RMS) in the frequency range between 2 and 3200 Hz. This range covers most of the frequencies that will occur for the majority of mechanical malfunctions and imperfections, for example unbalance and misalignment.

When used to measure bearing condition the Easy-Laser Vibrometer is measuring the effective acceleration (RMS) in the frequency range between 3200 and 20000 Hz. Trend analysis of the bearing condition value can be used to determine wear and tear of machine bearings.



See "Vibrometer (Optional)" on page 147.

Mount directly on machine

It is possible to remove the magnetic tip and mount the probe directly to the machine, using the M6 threaded stud.

Measuring tip

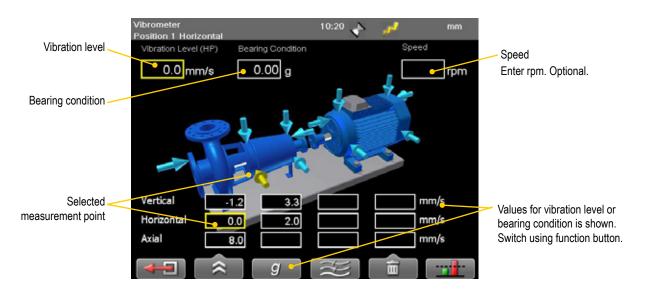
For measuring points that are hard to reach, use the measuring tip. Simply unscrew the magnetic tip and replace with the measuring tip. When measuring with the measuring tip, place it firmly against the measurement point and hold it as vertical, horizontal or axial as possible. When the measuring tip is used the frequency range is reduced to about 800 to 1500Hz.

Note!

Vibrometer is not included in all Shaft systems.

Measure

- 1. Use the standard red cable to connect the Vibrometer directly to the Display unit. Wireless units cannot be used.
- 2. Select **Select** to open the Vibrometer program.
 - Enter rpm. Optional.
 - Use the navigation buttons if you want to register another point than is selected by default.
- 3. Place the vibrometer against the measurement point. Pressing more firmly should not change the reading. If this happens, adjust the measuring point.
- 4. Wait ten seconds for the value to stabilize.
- 5. Press **OK** to register value.



Function buttons

	Leave program.
	See "Control panel" on page 15.
	Save, see "Measurement file handling" on page 11.
	Print report on thermal printer (optional equipment).
	Generate report. Available when you open a saved measurement.
g mm/s	Toggle button. Show values for bearing condition or vibration level.
	Toggle button. Show high frequency (10–3200 Hz) or low frequency (2–3200 Hz).
Ē	Contains a submenu Clear selected measurement point. Clear all measurement points.
.	Tolerance . Show tolerance table for vibration level and bearing condition value.

Vibration level

In the Display unit, a table from ISO 10816-3 standard is shown. This standard is used for machines with power above 15kW and nominal speeds between 120–15000 rpm.

- 1. Use navigation buttons to select a measurement point.
- 2. Select **Example** to open the tolerance table. It displays the values for the selected point.



Rigid or flexible

The ISO standard is classifying the machines differently if the machines have flexible or rigid foundations. Usually this is determined from drawings and calculations of the machine.

Groups

- Group 1. Large machines with rated power above 300kW. Electrical machines with shaft height H > 315mm. Operating speed ranges from 120 to 15000 rpm
- Group 2. Medium-sized machines with a rated power above 15kW up to and including 300kW. Electrical machines with shaft height between 160 < H < 315 mm. Operating speed normally above 600 rpm.
- Group 3. Pumps with multivane impeller and with separate driver with rated power above 15kW.
- Group 4. Pumps with multivane impeller and with integrated driver with rated power above 15kW.

Guideline

Another standard you can use is ISO 2372 class 4, for large machines on flexible foundations.

$0 - 3 \text{ mm/s} \\ 0 - 0.12 \text{inch/s}$	Small vibrations. None or very small bearing wear. Low noise level.
3 – 7 mm/s 0.12 – 0.27 inch/s	Noticeable vibration levels often concentrated to some specific part as well as direction of the machine. Noticeable bearing wear. Seal problems occur in pumps etc. Increased noise level. Plan action during next regular stop . Keep the machine under observation and measure at smaller time intervals than before to detect a deteriora- tion trend if any. Compare vibrations to other operating variables.
7 – 18 mm/s 0.27 – 0.71 inch/s	Large vibrations. Bearings running hot. Bearing wear-out cause frequent replacements. Seals wear out, leakage of all kinds evident. Cracks in weldings and concrete foundations. Screws and bolts are loosening. High noise level. Plan action soonest .
> 18 mm/s > 0.71 inch/s	Very large vibrations and high noise levels. This is detrimental to the safe operation of the machine. Stop operation if technically or economically possible considering the plant stop cost.

Bearing condition value

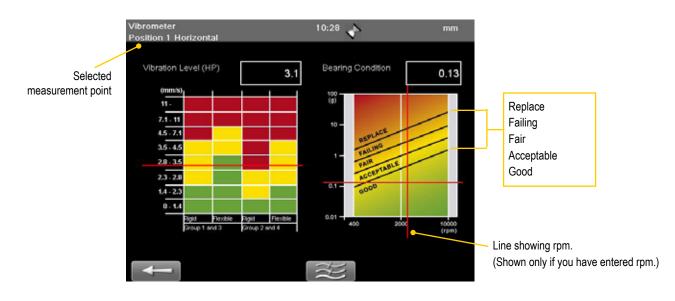
Bearing condition value is used for trend analysis. If the bearing condition value increases over time, it can be a sign that the bearing is poorly lubricated, overloaded due to misalignment or has a damaged surface. A high bearing condition value can however appear in gearboxes, converting machines with cutters and similar machines without any bearing fault. This is because this type of machinery naturally produces high frequency vibrations that are similar to the vibrations produced by a machine with a bearing fault.

The bearing condition value is the quadratic mean, RMS value, of all high frequency vibrations between 3200 Hz to 20000 Hz. This value is an acceleration average measured in multiples of the standard gravity constant, g.

The diagram below is only a guide to interpret the bearing condition value. A high bearing condition value should always be used as a request to make detailed frequency analysis. Do not change bearings before this is done.

Open tolerance table for bearing condition

- 1. Select a measurement point.
- 2. Select to open the tolerance table.

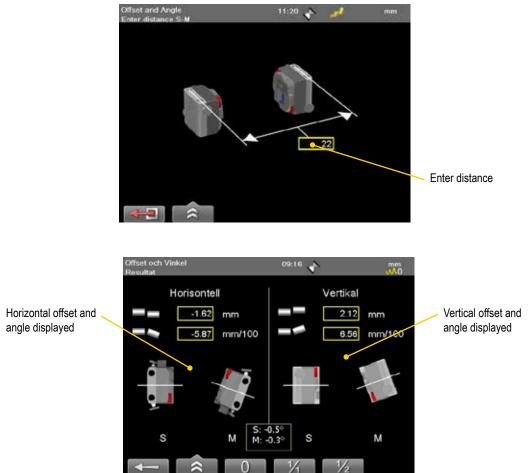


OFFSET AND ANGLE



The Offset and Angle program displays measurement values from measuring units S and M. The measurement values can be zeroed and any offset and angular changes between the units that may occur are displayed.

- 1. Enter distance between measuring units.
- 2. Press OK.



Function buttons

-	Leave program.
*	See "Control panel" on page 15. Show target. This is a quick way to see where the laser beam hits the target and how the measuring units are positioned.
0	Zero set. Set current value to zero.
1/1	Absolute. Return to absolute value.
1/2	Halve. Halve the displayed value.

BATTERY PACKS

When not using cable to the measuring units, you can use our chargeable battery pack. The battery pack comes in two versions, with or without built-in Bluetooth[®].

Battery pack

(Part No. 12-0617)

- 1. Place the battery pack on the rods.
- 2. Plug in the red cable to the measuring unit.

The measuring unit will charge and you can continue measuring.

This Battery pack does **not** have a builtin Bluetooth[®], you can however connect a Bluetooth[®] unit to the Detector/Measuring unit. To save energy, the Bluetooth[®] units will only connect when you are using a measurement program. There is no power switch on the Bluetooth[®] unit. To switch off, simply unplug it. The Bluetooth[®] unit have a serial number that is shown in the Bluetooth view in the Display unit.

Battery pack with Bluetooth®

(Part No. 12-0618)

This Battery pack has built-in Bluetooth® functionality. For more information on how to set up and search for Bluetooth® units, *see "Bluetooth*® *set up" on page 21*.

The Battery pack's serial number is placed on the backside. This serial number is shown in the Bluetooth view in the Display unit.

When the Battery pack run empty, the lights for Battery indicator and On/Off are switched off. However, the built-in Bluetooth[®] will still function as long as the Detector has some power left.



Battery indicator*

The battery indicator only shows the battery status of the Battery pack.

On/Off

Diode green when Battery pack is active. Diode yellow when no unit is connected. The Battery pack will automatically shut off.

Bluetooth® unit

Optional Diode yellow when attached correctly. Diode blue when Bluetooth[®] connection is established.

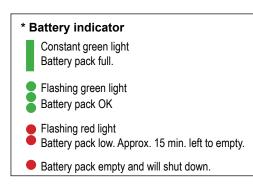
Battery indicator*

On/Off

Diode green when Battery pack is active. Diode yellow when no unit is connected. The Battery pack will automatically shut off.

Bluetooth[®] (only 12-0618)

Built-in functionality. Diode yellow when attached correctly. Diode blue when Bluetooth[®] connection is established.

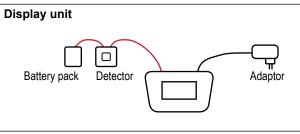


Charge battery pack

Using Display unit

It is possible to charge battery packs without Bluetooth[®] via the Display unit, one at a time. You can charge both a Detector and a battery pack by connecting the equipment as described in the image. If the Display unit is turned off while charging, the equipment will charge faster.

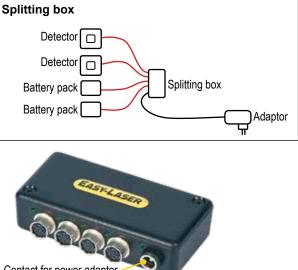
- 1. Connect the Display unit with the adaptor. The Display unit itself does not have enough power to charge the battery pack.
- 2. Use standard red cable to connect battery pack to the Display unit.



Using splitting box

When you have two battery packs or battery packs with Bluetooth®, you can use our splitting box (Part No. 12-0597).

- 1. Plug in the power adaptor to the splitting box. Use the standard power adaptor delivered with your system. All lights are lit up on the splitting box.
- 2. Plug in the battery pack and Detectors to the splitting box. Corresponding light is switched off.
- 3. When the battery pack is fully charged, the light is switched on again.



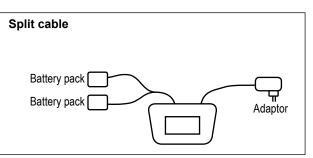
Contact for power adaptor

Using split cable

For two Battery packs or Battery packs with Bluetooth[®], you can also use our split cable (Part No. 12-0725).

The split cable can only be used to charge the Battery packs, not as a "red cable".

- 1. Plug in the power adaptor and split cable to the Display unit.
- 2. Plug in the battery packs.
- 3. When the battery packs are fully charged, the light is constant green on the Battery pack.



TECHNICAL DATA

System Easy-Laser® E710 Shaft, Part No. 12-0440

Ac	omplete system contains
1	Measuring unit M
1	Measuring unit S
1	Display unit
2	Bluetooth [®] units
2	Cables 2 m
2	Shaft brackets with chains
2	Extension chains
2	Magnet bases
2	Offset brackets
1	Set of rods 4x60 mm, 4x120 mm [4.72", 2.36"]
1	Manual
1	Measuring tape 3 m
1	USB memory stick
1	USB cable
1	Power adaptor (100–240 V AC)
1	Toolbox
1	Cleaning cloth for optics
1	CD with documentation
1	Carrying case
Sys	tem

System	
Relative humidity	10–95%
Weight (complete system)	10 kg [22 lbs]
Carrying case	WxHxD: 500x400x200 mm [19.7x15.7x7.8"]
	Drop tested. Water and dust tight.

Display unit E51

Part. no 12-0418

In the Display unit you are guided through the measurement procedure and can save and analyze the results.

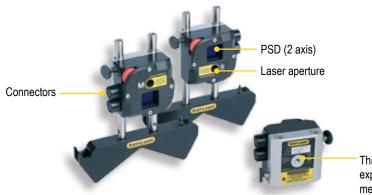


- A Connection for charger
- B Network connection
- C Expansion port
- D USBA E USBB
- F Easy-Laser® measurement equipment

Display unit		
Type of display/size	VGA 5.7" colour	
Displayed resolution	0.001 mm / 0.05 thou	
Power management	Endurio TM system for unbroken power supply	
Internal battery (stationary)	Li Ion, Not restricted PI967, 3.7 volt, 43Wh, 11600 mAh	
Battery compartment	For 4 pcs R 14 (C)	
Operating time	Appro. 30 hours (Normal operating cycle)	
Connections	USB A, USB B, External, Easy-Laser® units, Network	
Storage memory	>100,000 measurements	
Help functions	Calculator, Converter	
Environmental protection	IP Class 65	
Housing material	PC/ABS + TPE	
Dimensions	WxHxD: 250x175x63 mm [9.8x6.9x2.5"]	
Weight (without batteries)	1030 g [2.3 lbs]	
Cables		
Туре	With Push/Pull connectors	
System cable	Length 2 m [78.7"]	
Extension system cable	Length 5 m [196.8"]	
USB cable	Length 1.8 m [70.8"]	
EasyLink [™] data base software for PC		
Minimum requirements	Windows® XP, Vista, 7. For the export functions, Excel 2003 or newer must be installed on the PC.	

Measuring units

Part no. 12-0433 Part no. 12-0434



Threaded fixing hole for future expansion and more measurement possibilities

Measuring units		
Type of display/size	2-axis PSD 20x20 mm [0.78" sq]	
Detector resolution	0.001 mm / 0.05 thou	
Type of laser	Diode laser	
Laser wavelength	635–670 nm	
Laser safety class	Class 2	
Laser output power	<1 mW	
Inclinometers	0.1° resolution	
Thermal sensors	$\pm 1^{\circ} C$ accuracy	
Environmental protection	IP Class 66 and 67	
Dimensions	BxHxD: 60x60x42 mm [2.36x2.36x1.65"]	
Weight	202 g [0.45 lbs]	
Internal battery	LI-Po, 3.7 volt, 2.5Wh, 680mAh	
Wireless connection unit (Not included for all systems)		
Wireless communication	Class I Bluetooth® Wireless Technology	
Operating temperature	-10–50 °C	
Housing material	ABS	
Environmental protection	IP Class 66 and 67	
Dimensions	53x32x24 mm [2.1x1.2x0.9"]	
Weight	25 g [0.06 lbs]	

Bluetooth®

Diode yellow when attachedcorrectly.

Diode blue when Bluetooth[®] connection is established.



Note!

The Bluetooth[®] unit is powered by the Detector. To save energy, the Bluetooth[®] connection is only established when you are using a measurement program.

BTA E180 (Optional)

Part no. 12-0796

Clean the units and the windows at the apertures with a dry cotton cloth. If not using the system for a long period of time, remove the battery from the laser transmitter.



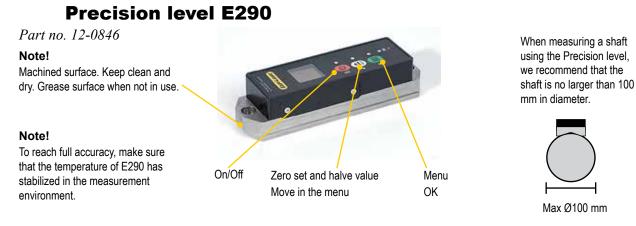
Laser transmitter E180	
Sheave diameter	> Ø 60 mm [2.5"]
Laser class	2
Output power	<1 mW
Laser wavelength	635–670 nm
Beam angle	60°
Accuracy	Parallelity: < 0.05°,
	Offset < 0.2 mm [0.008"]
Battery type	1xR6 (AA) 1.5 V
Battery operation	8 hours cont.
Operating temperature	-10°C to +50°C
Material	ABS plastics / Hard anodized aluminium
Dimensions BxHxD	145x86x30 mm [5.7x3.4x1.2"]
Weight	270 g [9.52 oz]
Detector unit E180	
Sheave diameter	> Ø 60 mm [2.5"]
Displayed resolution	(Changeable between mm/inch)
	Axial offset: 0.1 mm [0.005"]
	Angular value: 0.1°
Measurement distance	Up to 3 m [9.8'] between transmitter and detector
Measurement range	Axial offset: ±3 mm [0.12"] Angular value: ±8°
Display resolution	Offset: 0.1° Angle:0.01°
Display type	Yellow OLED 96x96 pixels
Connection	Bluetooth® wireless technology
Battery type	Li-Ion
Battery operation	5 hours continuously
Housing material	ABS plastics / Anodized aluminium
Dimensions BxHxD	95x95x36 mm [3.7x3.7x1.4"]
Weight	190 g [6.7 oz]

Vibrometer (Optional)

Part no. 12-0654



Instrument/Software	
Measurement range	0-50 mm/s [0-2 inch/s] RMS
Resolution	0.1 mm/s [0.005 inch/s]
Frequency range	Total level: 2–3200 Hz (Lp), 10–3200 Hz (Hp)
	Bearing condition: 3200–20000 Hz
Probe	
Sensitivity	100 mV/g ±10%
Dimensions	Magnet: L=20 mm [4/5"], ∅ =15 mm [19/32"] Gauge tip: L=65 mm [2 1/2"9]



Change unit

Press and select "Unit". Choose from the following units: mm/m, inch/foot, degrees or arc sec. Use (1) to move in the menu.

Calibration

The Precision level is calibrated on the factory. To calibrated on site:

- 1. Place the Precision level on a roll (or the object you are going to measure). Make a mark to ensure that you place the Precision level in the same position.
- 2. Press **()** and select "Calibration".
- 3. Wait until the value has stabilized. Press 🧲
- 4. Rotate the Precision level 180°. Wait until the value has stabilized.
- 5. Press (). The Precision level has been calibrated. The calibration is saved even when the Precision level is switched off.

Factory recall

Press e and select "Fac. recall" to return to factory settings.

Visible

By default the precision level is set to visible. This means it will be shown when searching for Bluetooth units. To save energy, the precision level is set to not visible once a Bluetooth connection is established.

Connect to Display unit

Connect the Precision level to the Display unit via Bluetooth[®].

Precision level E290		
Resolution	0.01 mm/m (0.0001°)	
Range	$\pm 2 \text{ mm/m}$	
Measurement error	Range ± 1 mm/m: accuracy within ± 0.02 mm/m of displayed value.	
	Range ± 2 mm/m: accuracy within ± 0.04 mm/m of displayed value.	
Type of display	OLED	
Wireless communication	Class I Bluetooth® wireless technology	
Environmental protection	IP Class 67	
Operating temperature	-10–50 °C	
Internal battery	Li Po	
Material	Hardened, polished and corrosion resistance steel, ABS plastics	
Dimensions	WxHxD: 149x40x35 mm [5.9x1.6x1.4"]	
Weight	530 g [18.7oz]	

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